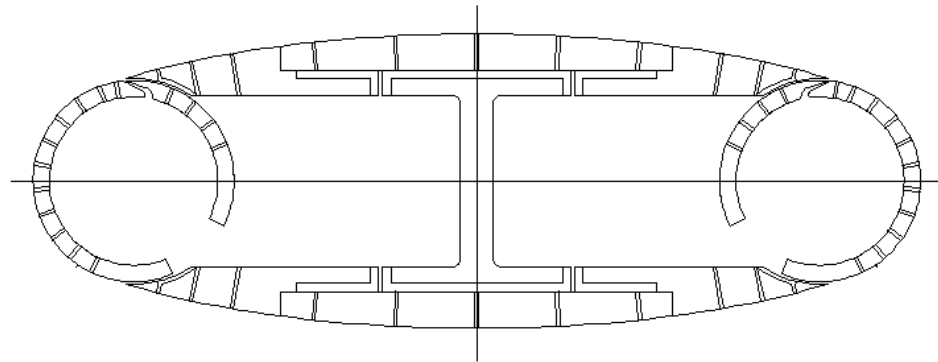




APPLICATION OF CFD ON A BLUNT ELLIPTICAL AIRFOIL



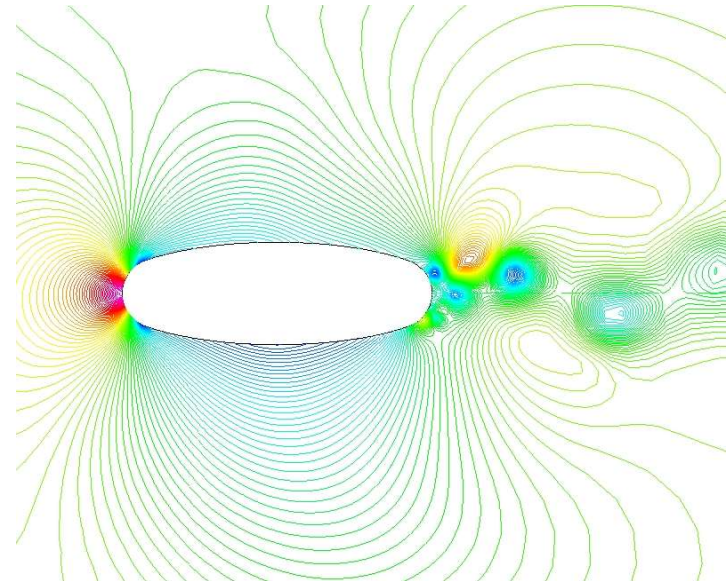
Cristina Bhamburkar

6/16/2009

Outline

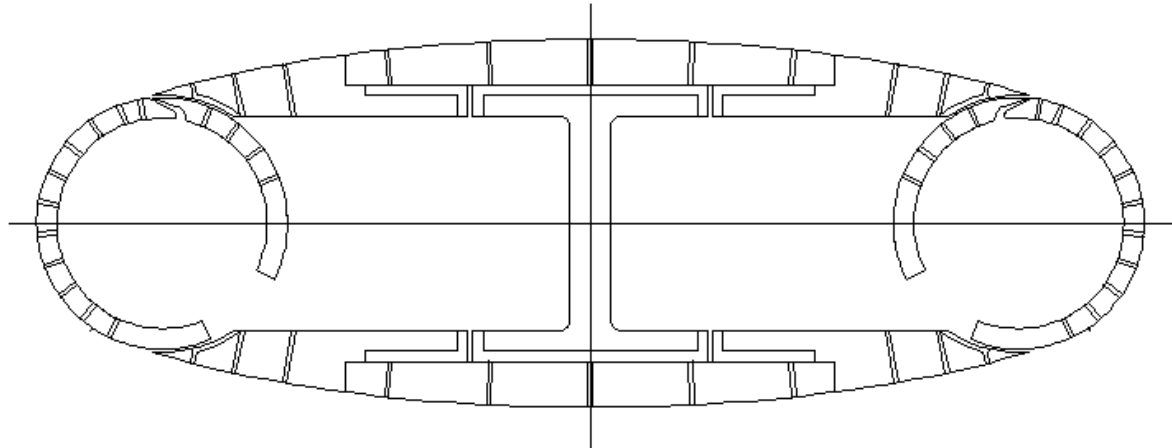


- Setup
- Results
 - Code Validation
 - Baseline Flow
 - Active Flow Control
 - Time averaged behavior
 - Code Issues
 - Turbulence Models
 - Time dependent behavior
- Comparisons
 - Time averaged behavior compared to results from the Aerodynamics Laboratory
 - Experimental results are not performed in this paper
- Conclusions



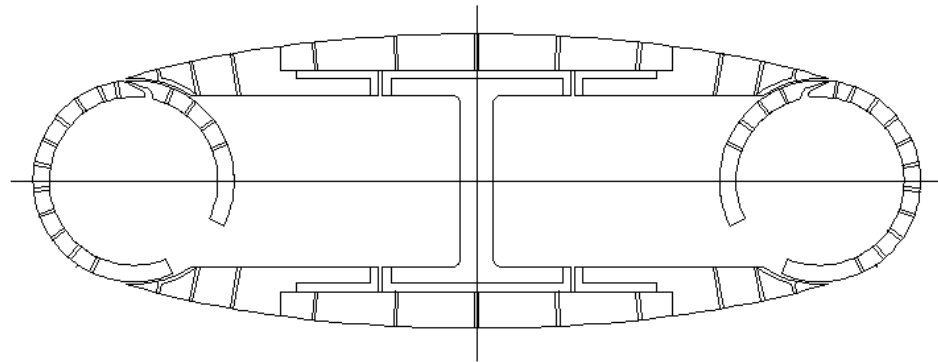
Setup

- 2D elliptical airfoil model
 - Circular cylinders at leading and trailing edges
 - Cylinders can be rotated
 - Circular cylinders are fitted with slots
 - Slot widths can be varied
 - Allows various options for active flow control experiments
- The chord length of the airfoil is approximately 27cm
- Roughness strips are placed at 3cm (11% chord)
 - On upper and lower surfaces





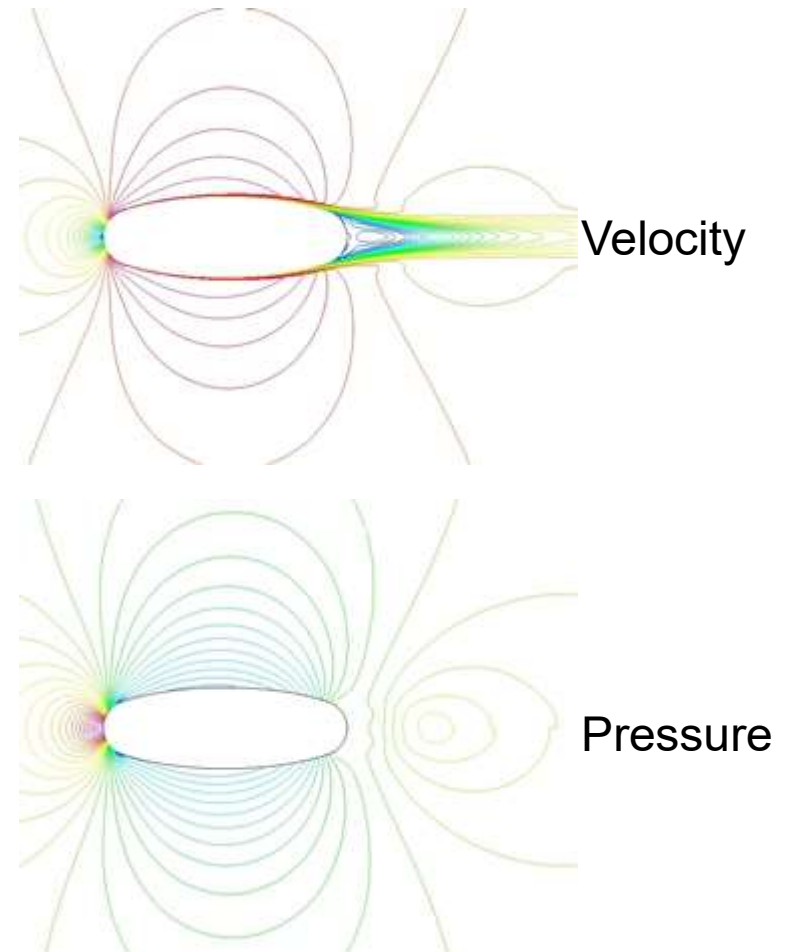
Baseline Flow



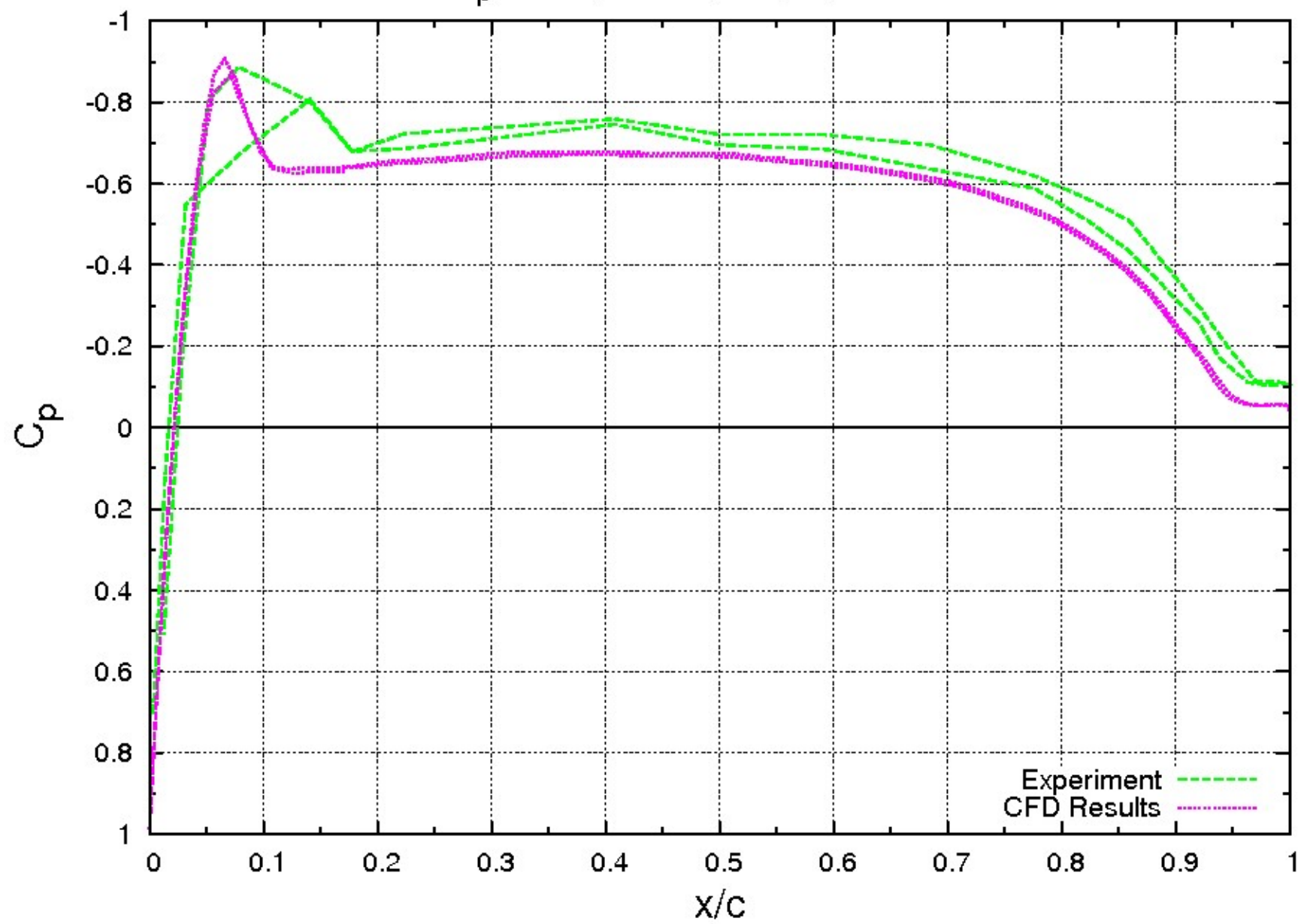


Velocity + Pressure Contours

- Baseline solution
 - angle of attack was varied from 0 to 20 degrees
- Contour plots generated
 - contours are lines of constant magnitude
- Velocity contours
 - blue lines – zero velocity
 - red lines – high velocity
- Pressure contours
 - blue lines – low pressure
 - red lines – high pressure
- Pressure coefficient vs. x/c



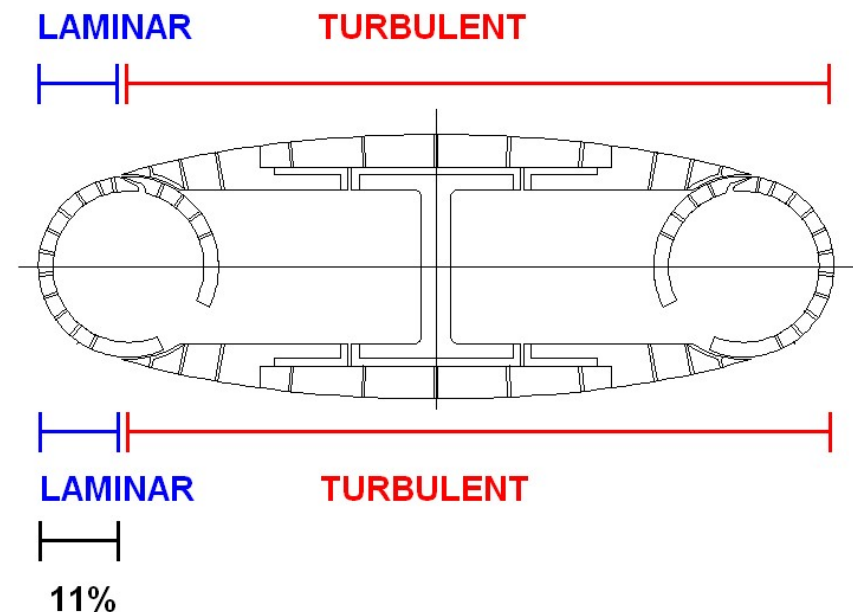
C_p vs. x/c , $\alpha = 0^\circ$, Ellipse, $U=15\text{m/s}$



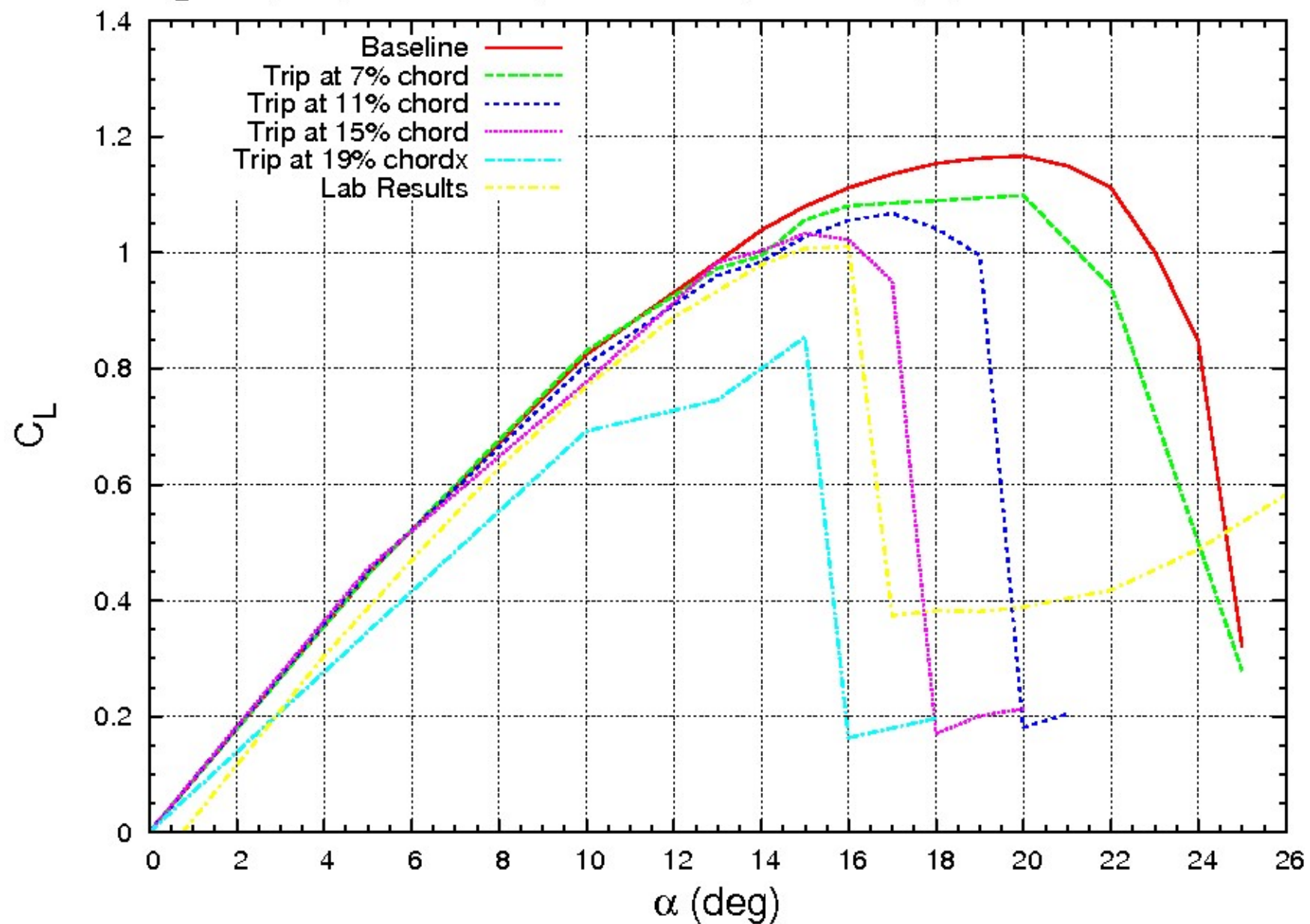


Comparison of Trip Locations

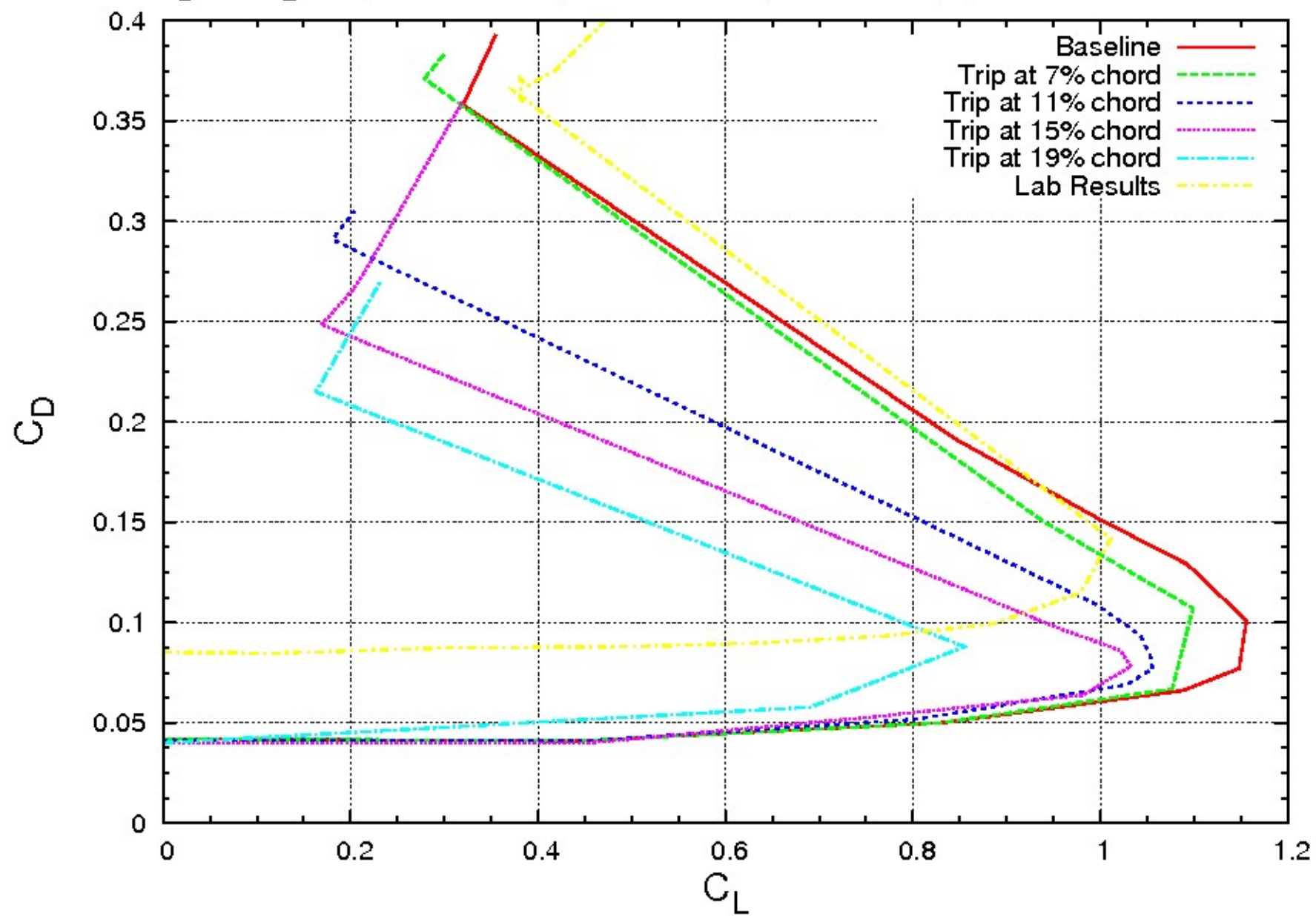
- A trip is simulated by defining a laminar region at the leading edge
- The grid points outside this region were run turbulent
- Laminar-turbulent transition is simulated at
 - 7%, 11%, 15%, 19% chord
- In the lab, the ellipse is tripped at 11% chord



C_L vs. α , Ellipse M=0.044, $Re=2.46 \times 10^5$, $U=15$ m/s, Spalart-Allmaras Model



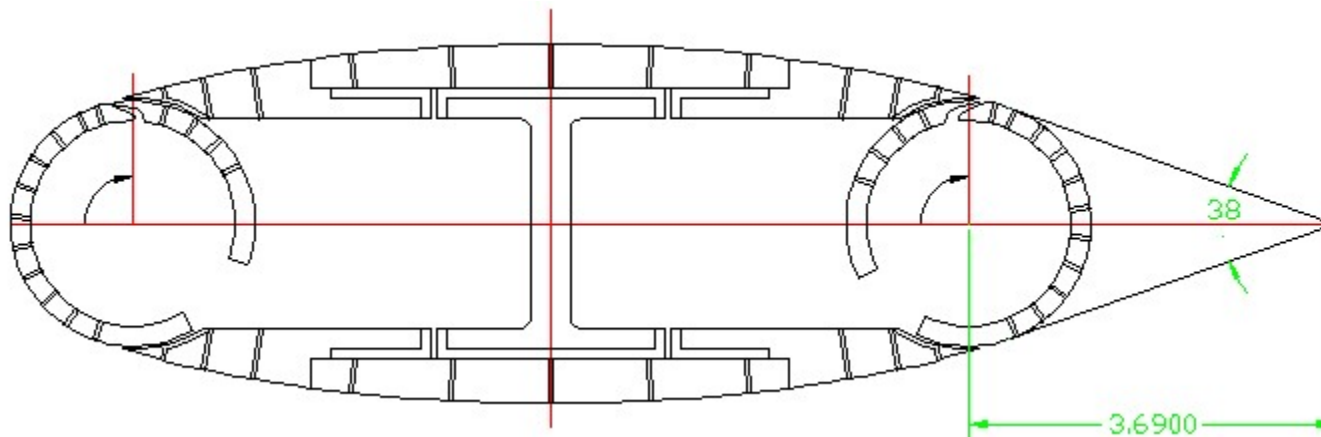
C_D vs. C_L , Ellipse $M=0.044$, $Re=2.46 \cdot 10^5$, $U=15$ m/s, Spalart-Allmaras Model



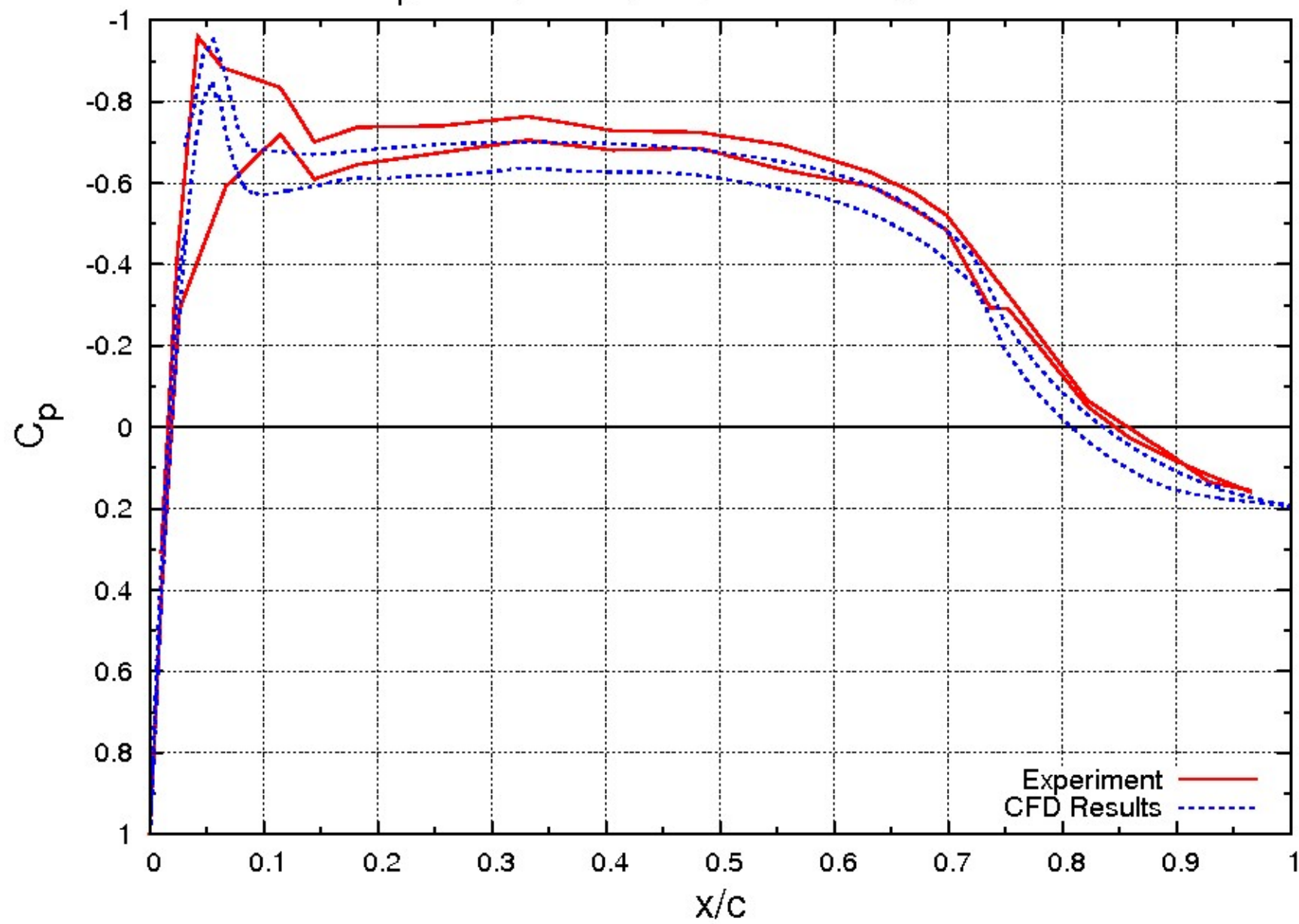


Ellipse with a Cusp

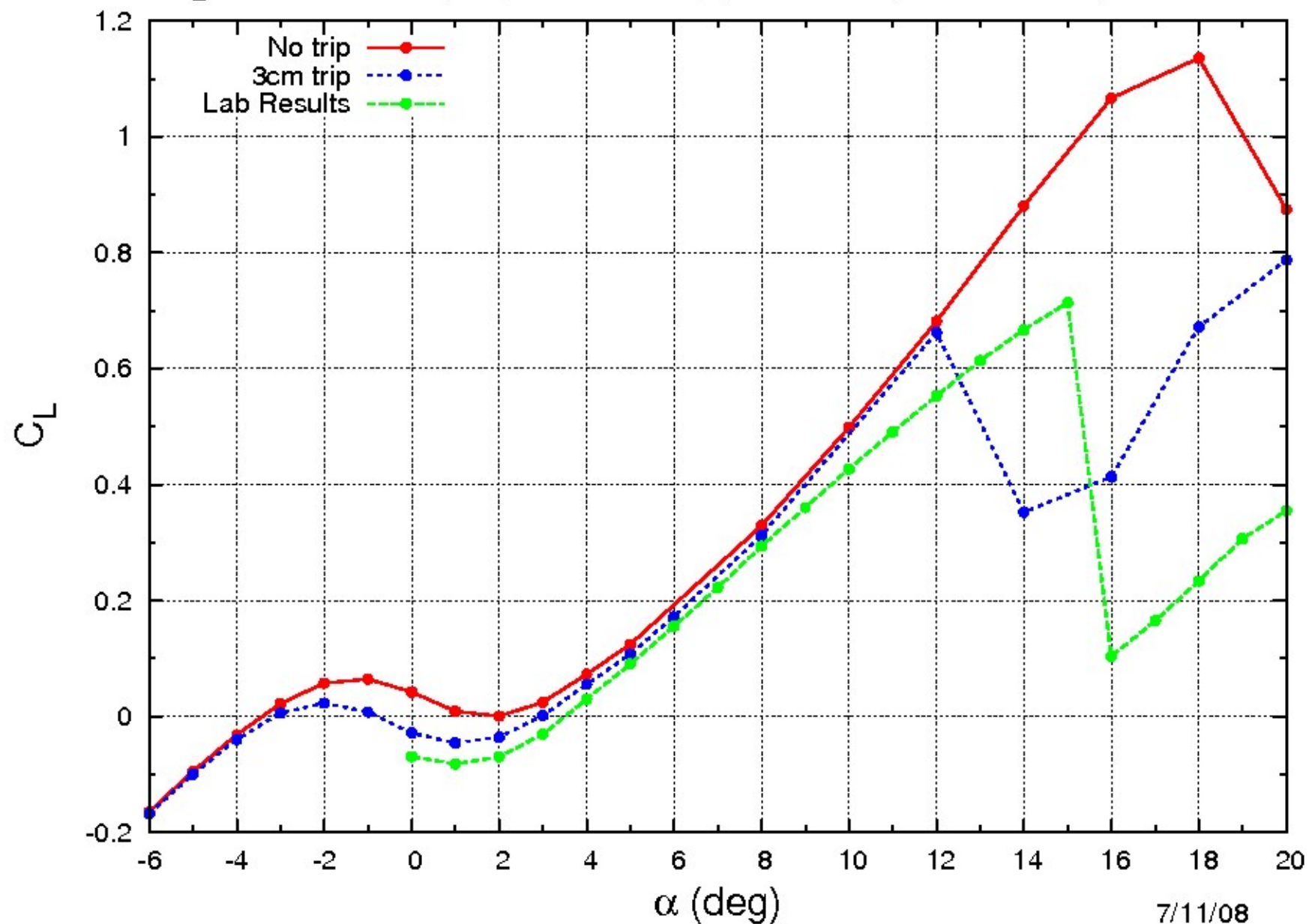
- A triangular cusp was added to the trailing edge
- The cusp enforces the Kutta condition
 - drastically changes the behavior of the airfoil
- The height is approximately 3.69"
- The two sides make a 38 degree angle



C_p vs. x/c , $\alpha = 0^\circ$, Ellipse with Cusp, $U=15\text{m/s}$



C_L vs. α . Baseline, Ellipse with Cusp, $M=0.0436$, $Re=3.35 \times 10^5$, $U=15$ m/s

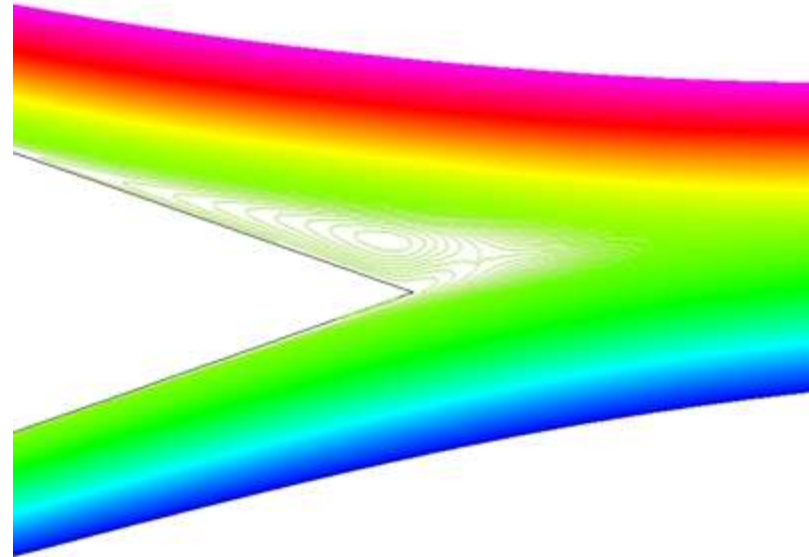


7/11/08



Cusp Observations

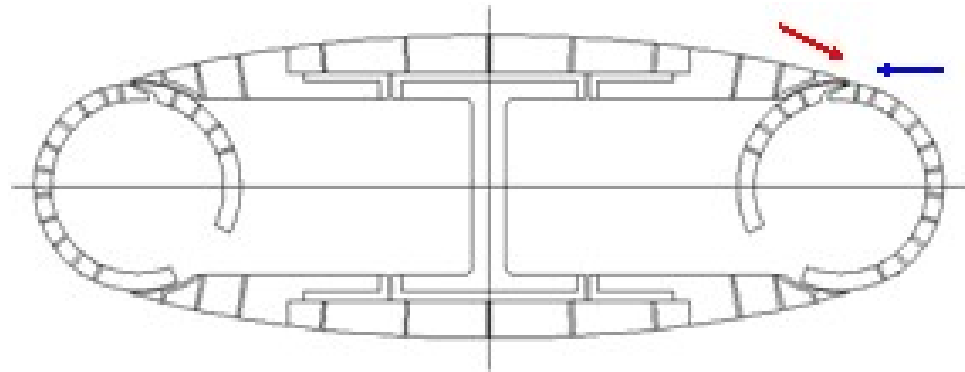
- About the geometry
 - High thickness ratio
 - High trailing edge angle
- At low angles of attack the boundary layer switches from one side to the other
 - There is growth at the upper surface
 - There is attached flow at the lower surface
- Suction is so strong that it produces a negative lift-curve slope



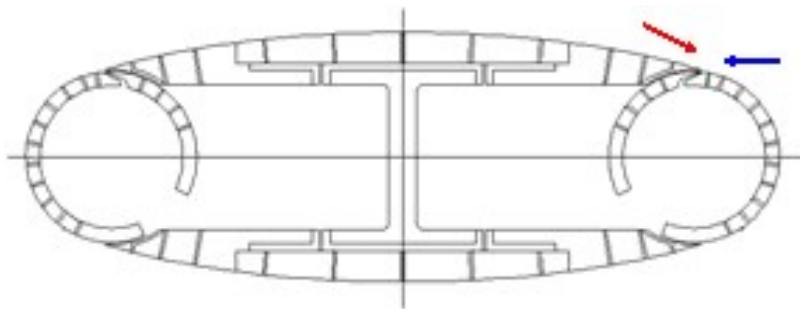
Streamlines, AOA = 2 degrees



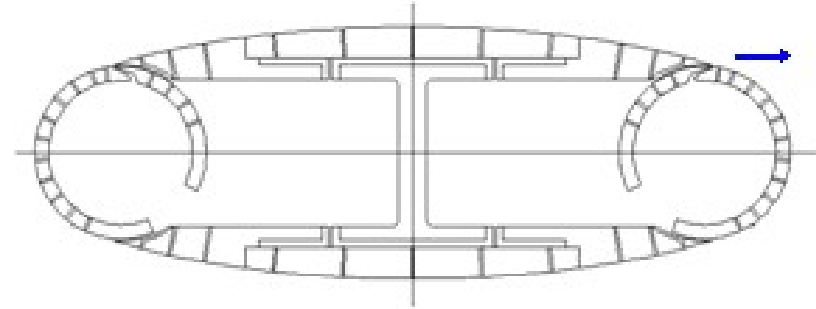
Active Flow Control



Trailing Edge Blowing and Suction



Suction **Upstream** and **Downstream**

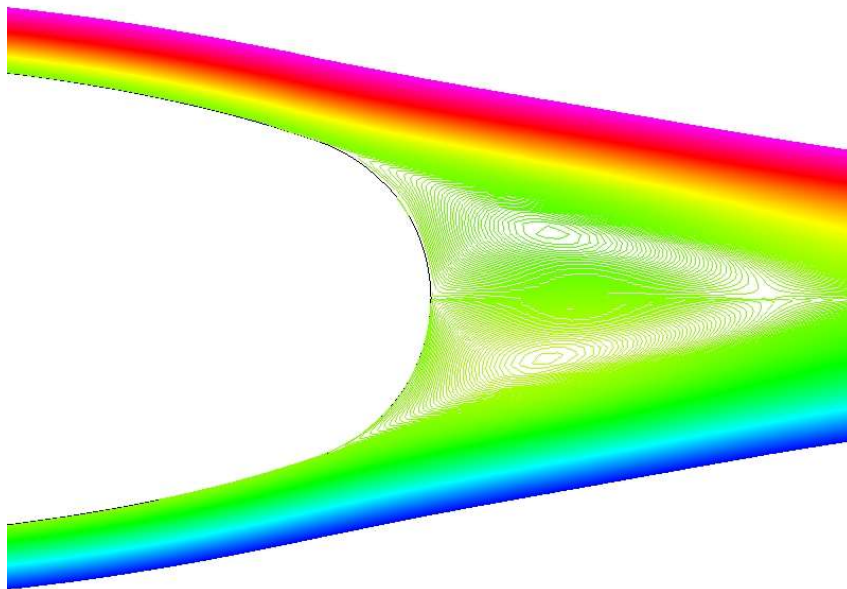


Blowing **Downstream**

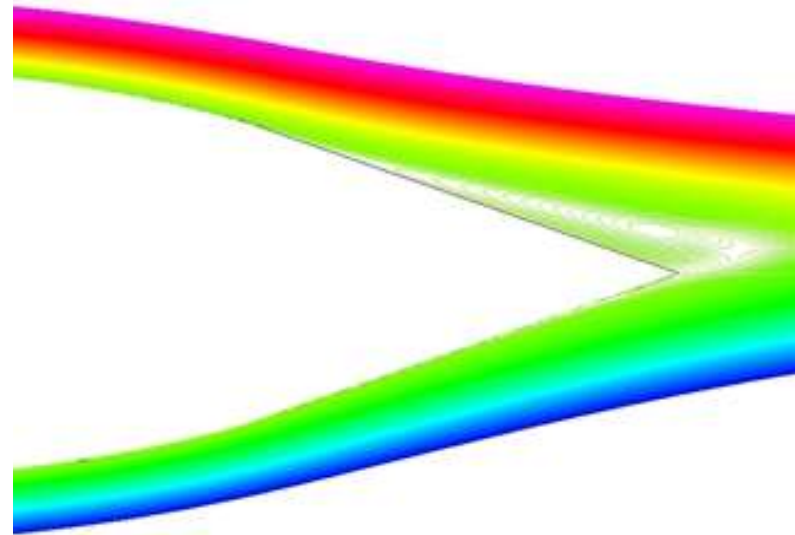
- Slot is pointed either upstream or downstream
- Slot width was varied from 15/1000 inch to 90/1000 inch
- Momentum coefficient was varied between 0% and 8%

$$C_{\mu} = \rho_J U_J^2 h / (\frac{1}{2} \rho_{\infty} U_{\infty}^2 c)$$

Steady Blowing, Streamlines

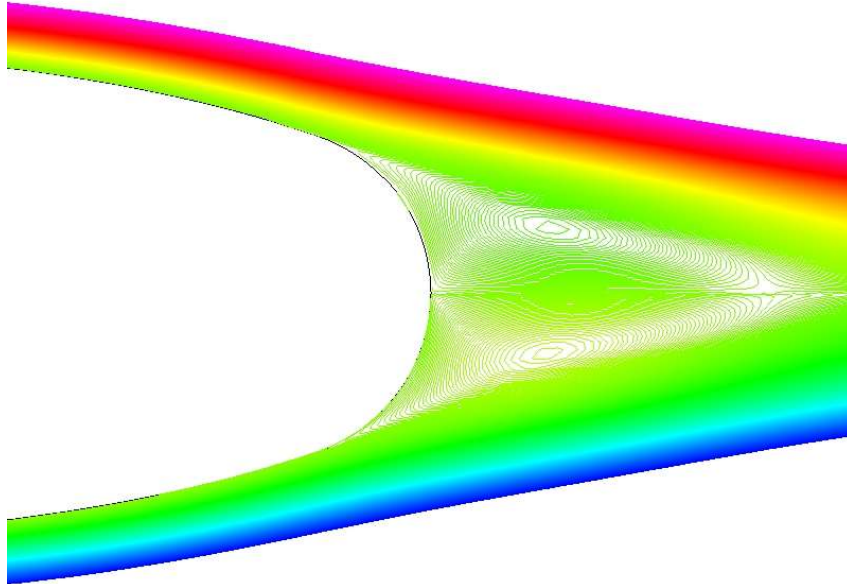


$C_\mu = 1\%$, $h=15/1000$ inch

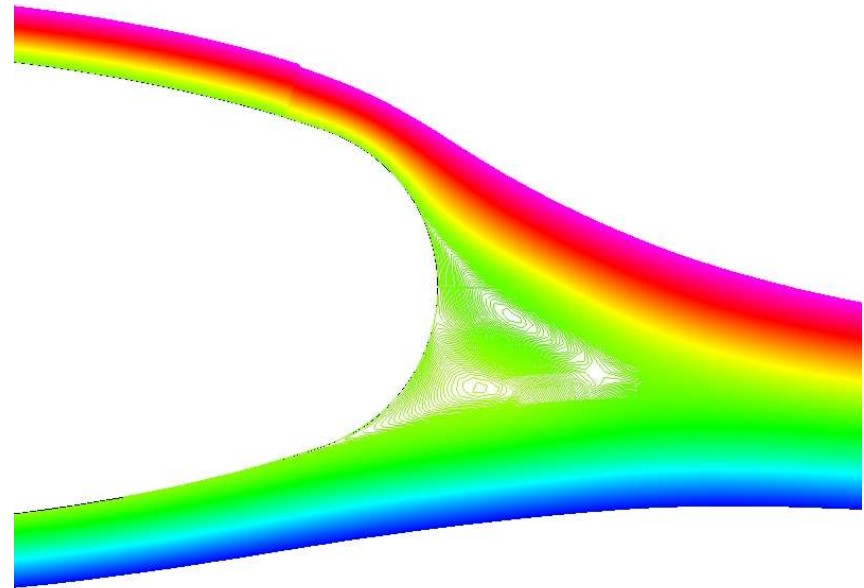


$C_\mu = 1\%$, $h=15/1000$ inch

Steady Blowing, Streamlines

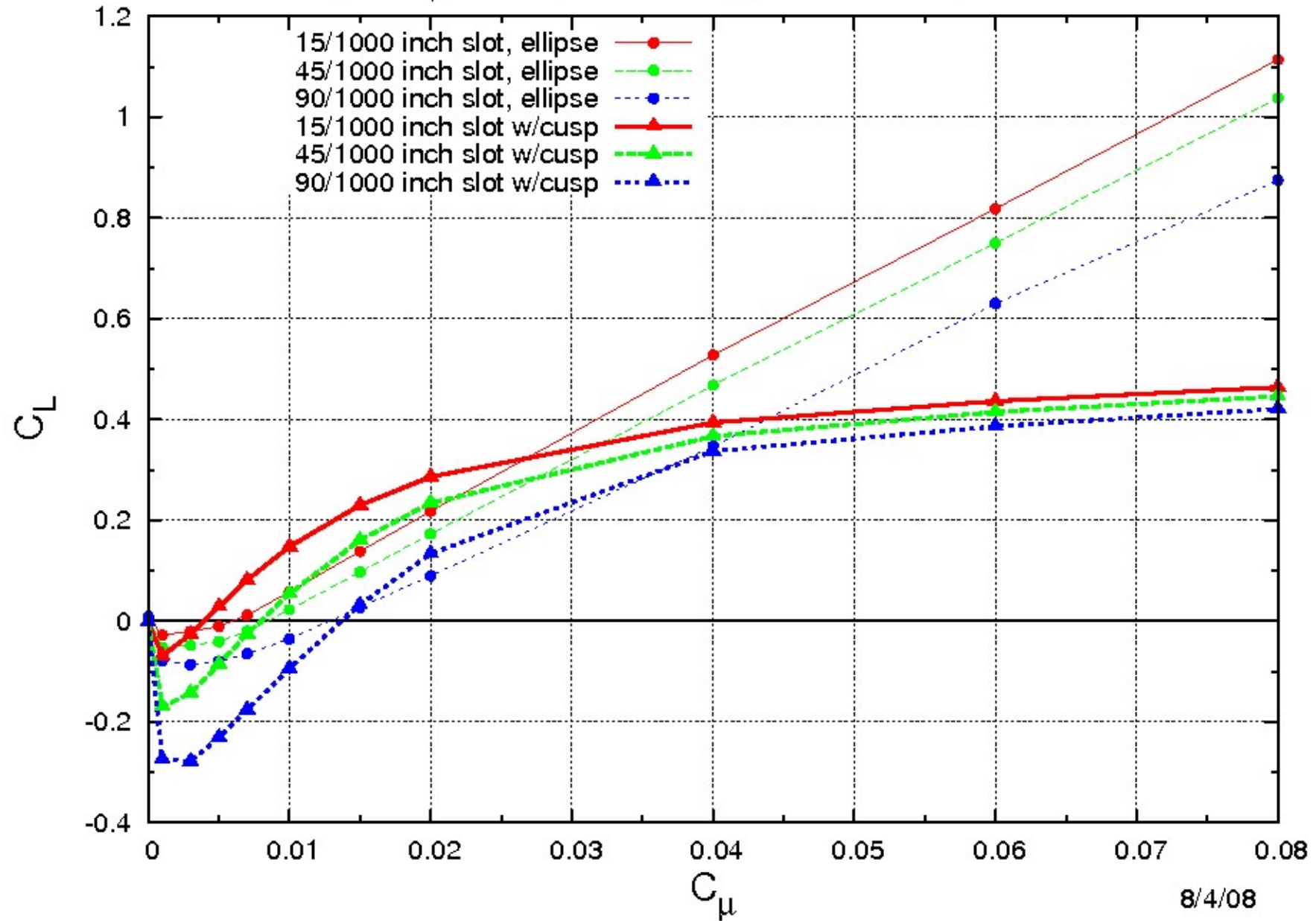


$C_\mu = 1\%$, $h=15/1000$ inch

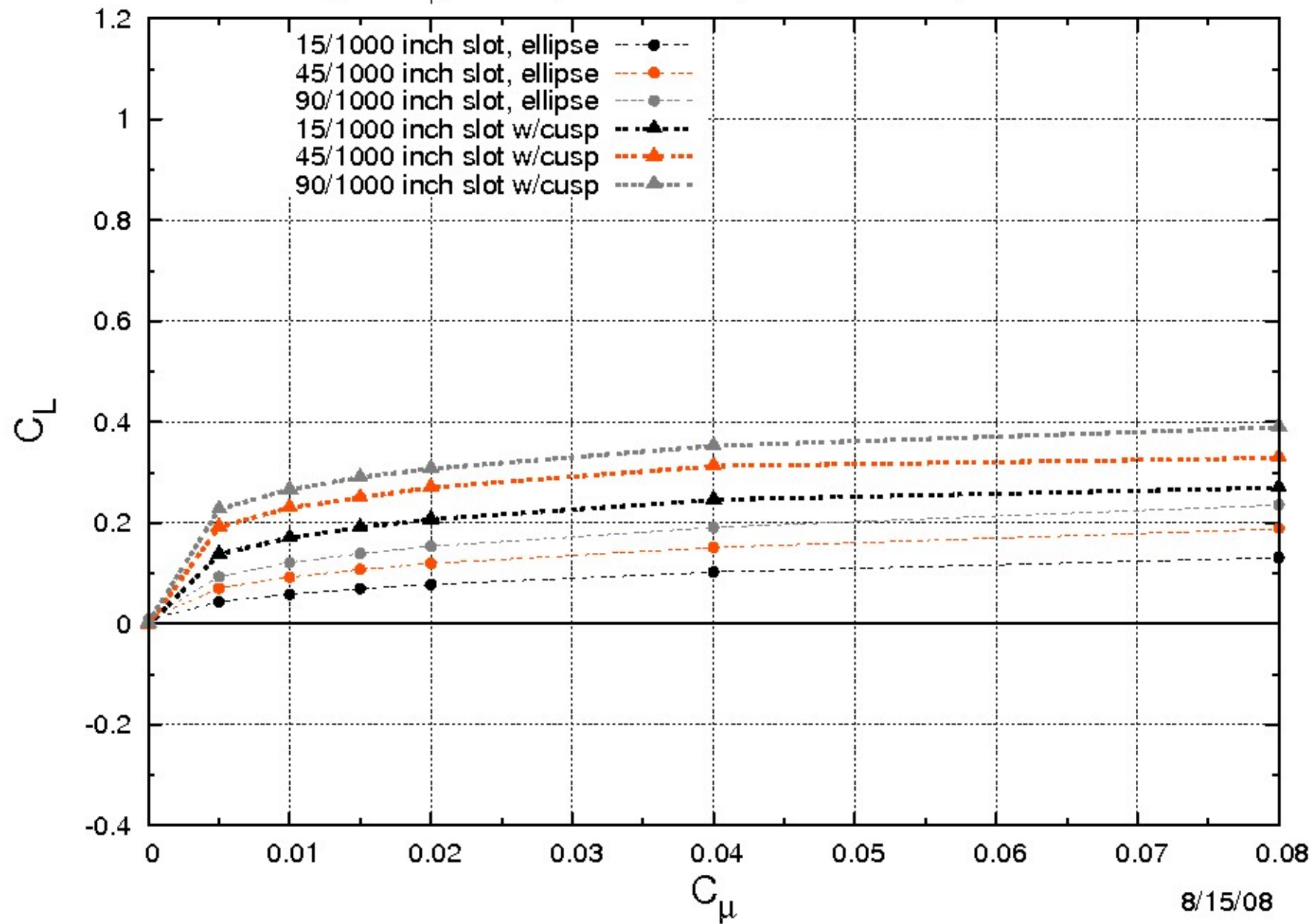


$C_\mu = 8\%$, $h=15/1000$ inch

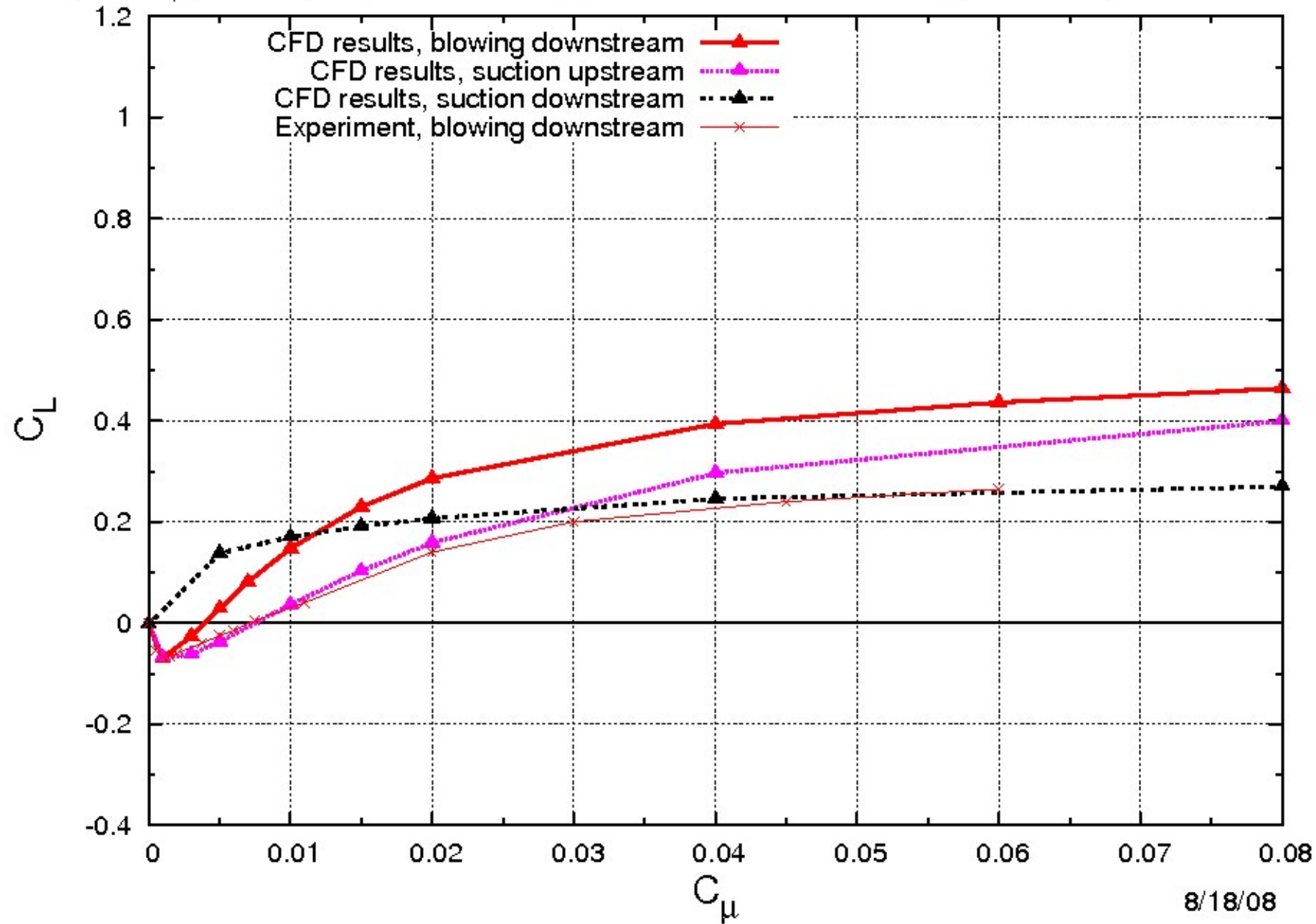
C_L vs. C_μ , $\alpha = 0^\circ$, TE Blowing, Downstream, $U=15$ m/s



C_L vs. C_μ , $\alpha = 0^\circ$, TE Suction, Downstream, $U=15$ m/s

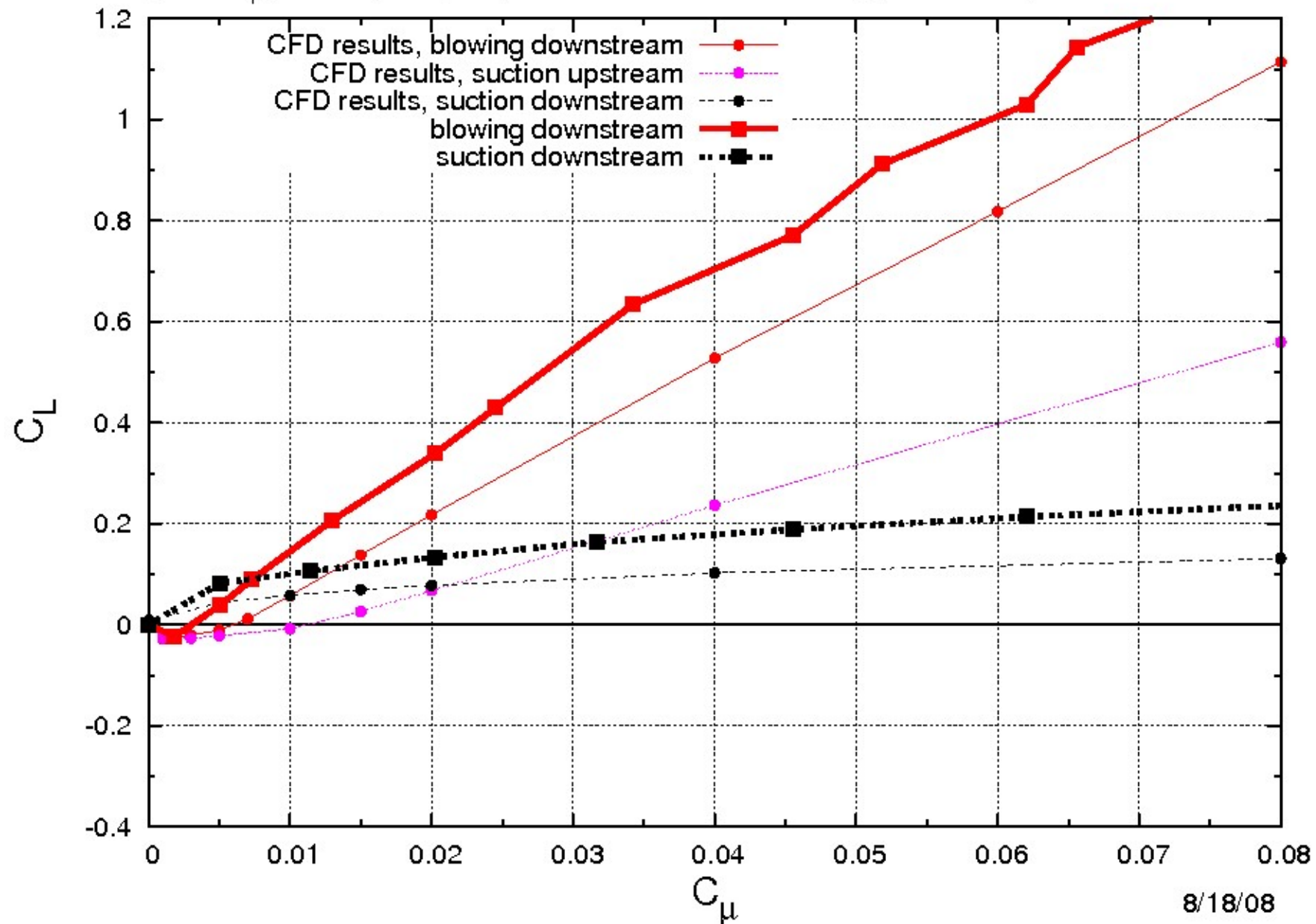


C_L vs. C_μ , $\alpha = 0^\circ$, Ellipse with Cusp, TE Suction and Blowing, $U=15\text{m/s}$, 15/1000 inch slot



8/18/08

C_L vs. C_μ , $\alpha = 0^\circ$, Ellipse, TE Suction and Blowing, $U=15\text{m/s}$, 15/1000 inch slot

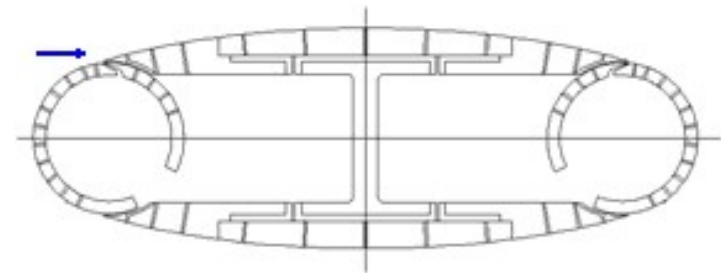


8/18/08

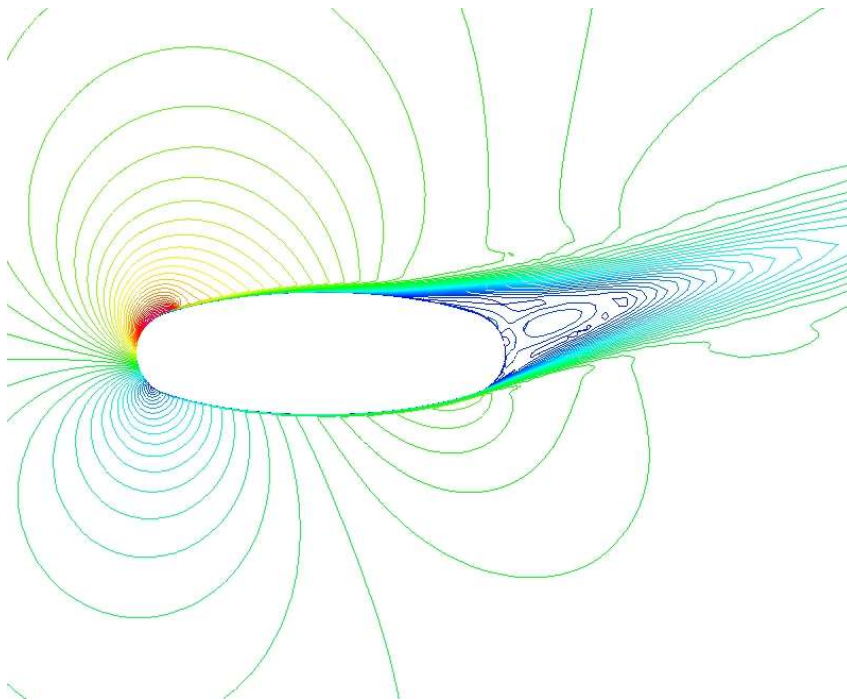


Leading Edge Suction

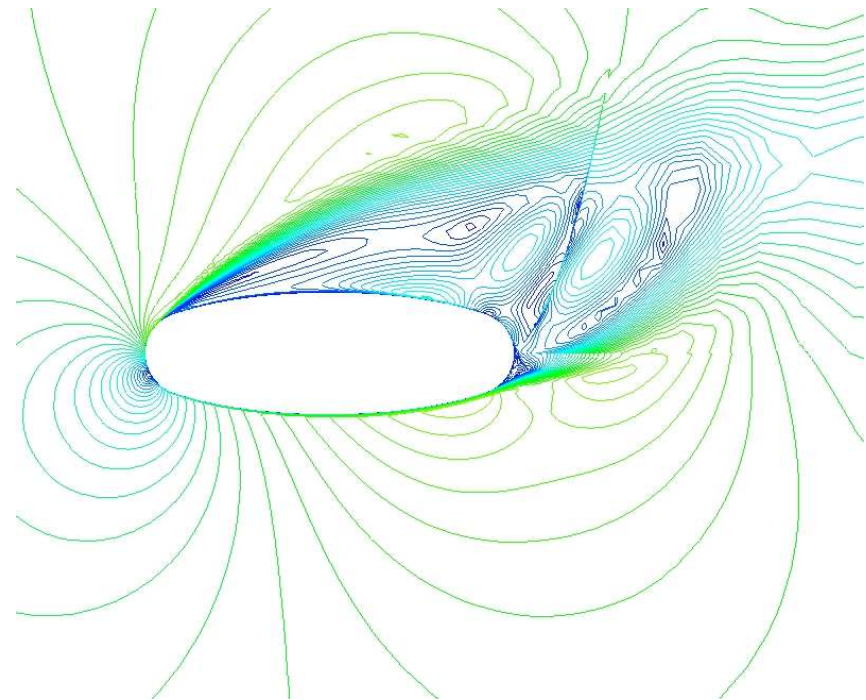
- Effects of steady suction
 - Significantly delays stall
 - Significantly increases lift
- Steady suction hysteresis
 - How will the airfoil stall if steady suction is turned off?
 - How will the airfoil recover from stall if suction is turned on?



With and Without Suction

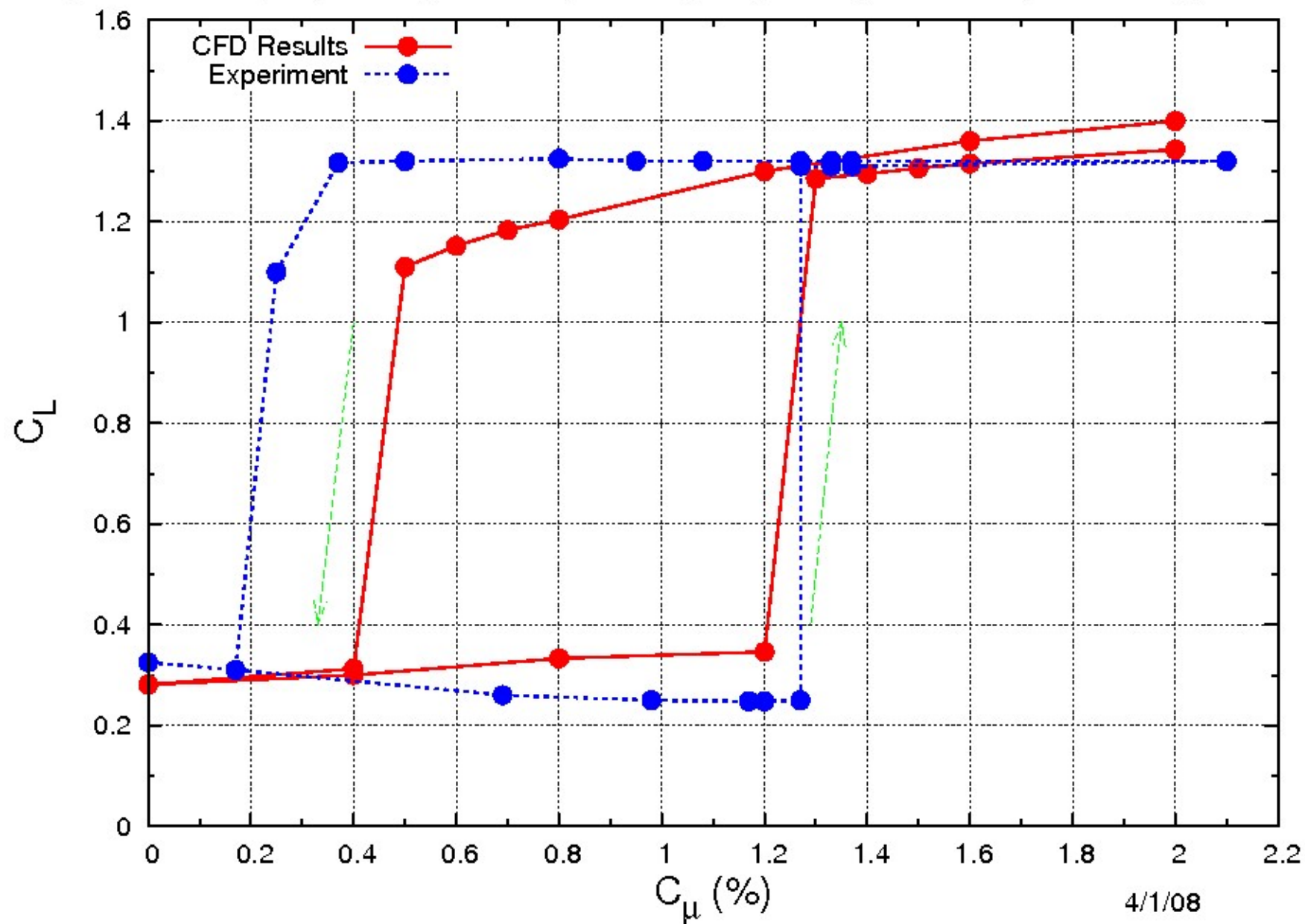


$\alpha = 19$ degrees, $C_{\mu} = 2\%$

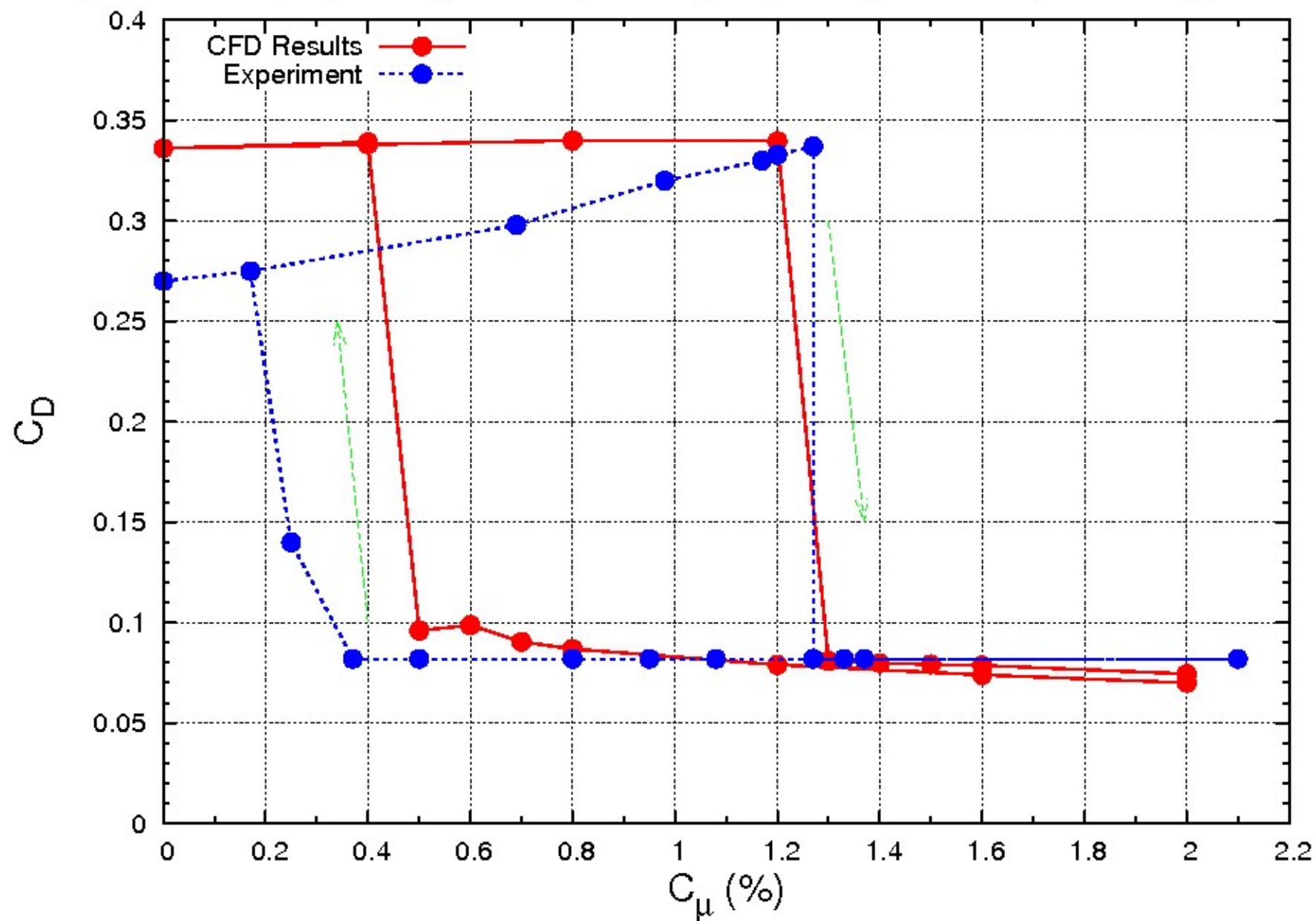


$\alpha = 19$ degrees, $C_{\mu} = 0\%$

Hysteresis: Ellipse, Steady Suction, Leading Edge Slot, $h/R=1.2\%$, $\alpha=19^\circ$, $Re=3.3 \times 10^5$



Hysteresis: Ellipse, Steady Suction, Leading Edge Slot, $h/R=1.2\%$, $\alpha=19^\circ$, $Re=3.3 \times 10^5$



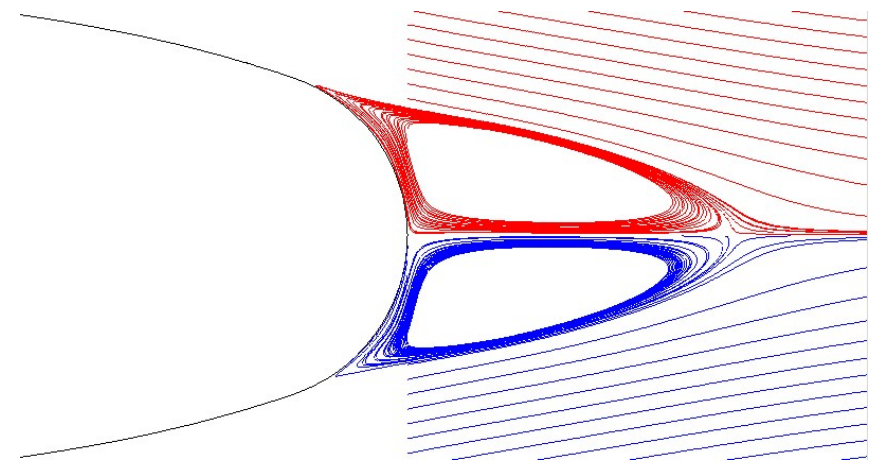


Time Accurate Results



Zero Angle of Attack

- Theory
 - Blunt trailing edge
 - Similar to circular cylinder
 - Solution oscillates
- CFD
 - Solution is steady
 - Spalart-Allmaras model
 - Flow field is characteristic of low Reynolds numbers
 $Re = 3000$



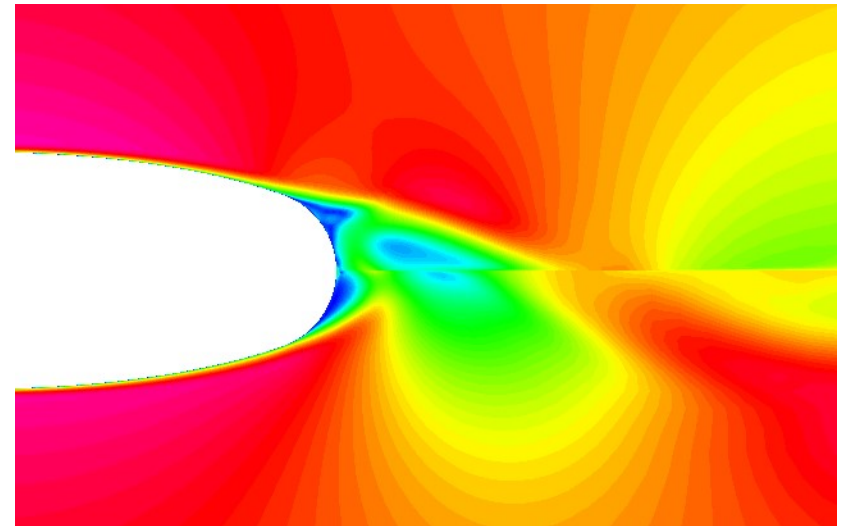
dt = 0.01

ncyc = 8



Zero Angle of Attack

- Is the time step too low?
 - dt was increased to 1.00
 - Solution oscillates
- Poor solution
 - Residuals were high
 - Oscillations too large
 - Solution not resolved at boundaries



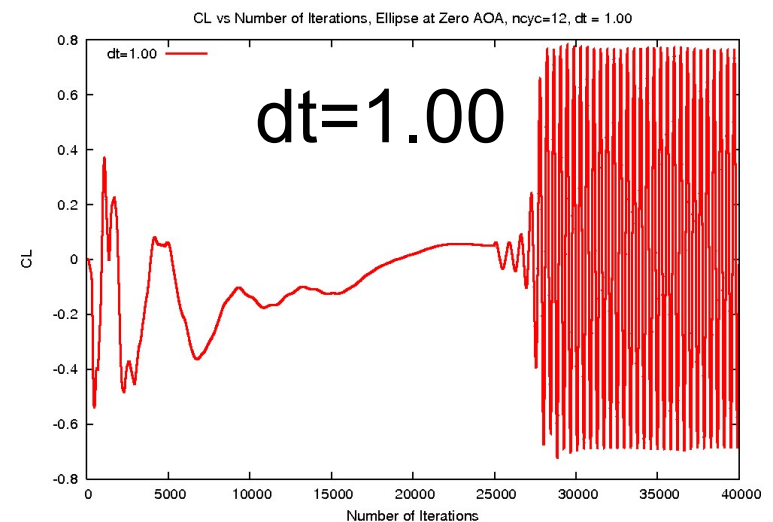
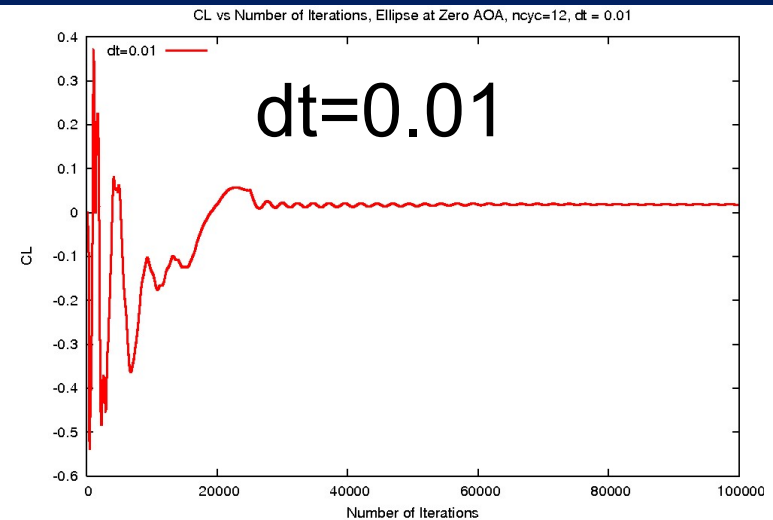
dt = 1.00

ncyc = 8

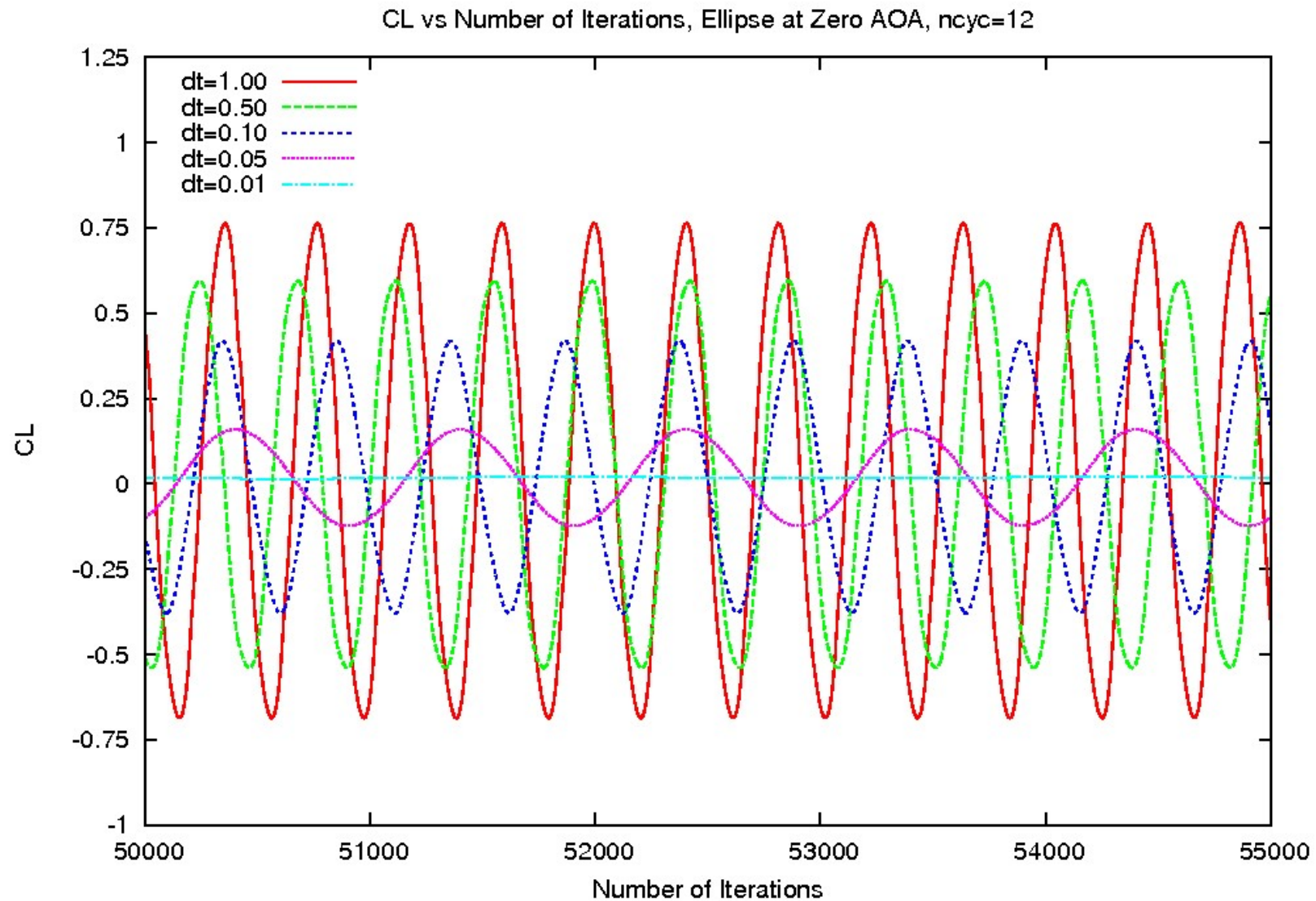


Zero Angle of Attack

- How does the solution change with dt ?
- Lift coefficient was plotted vs. iterations
- Observe the plots
 - Two values of dt
 - No other changes

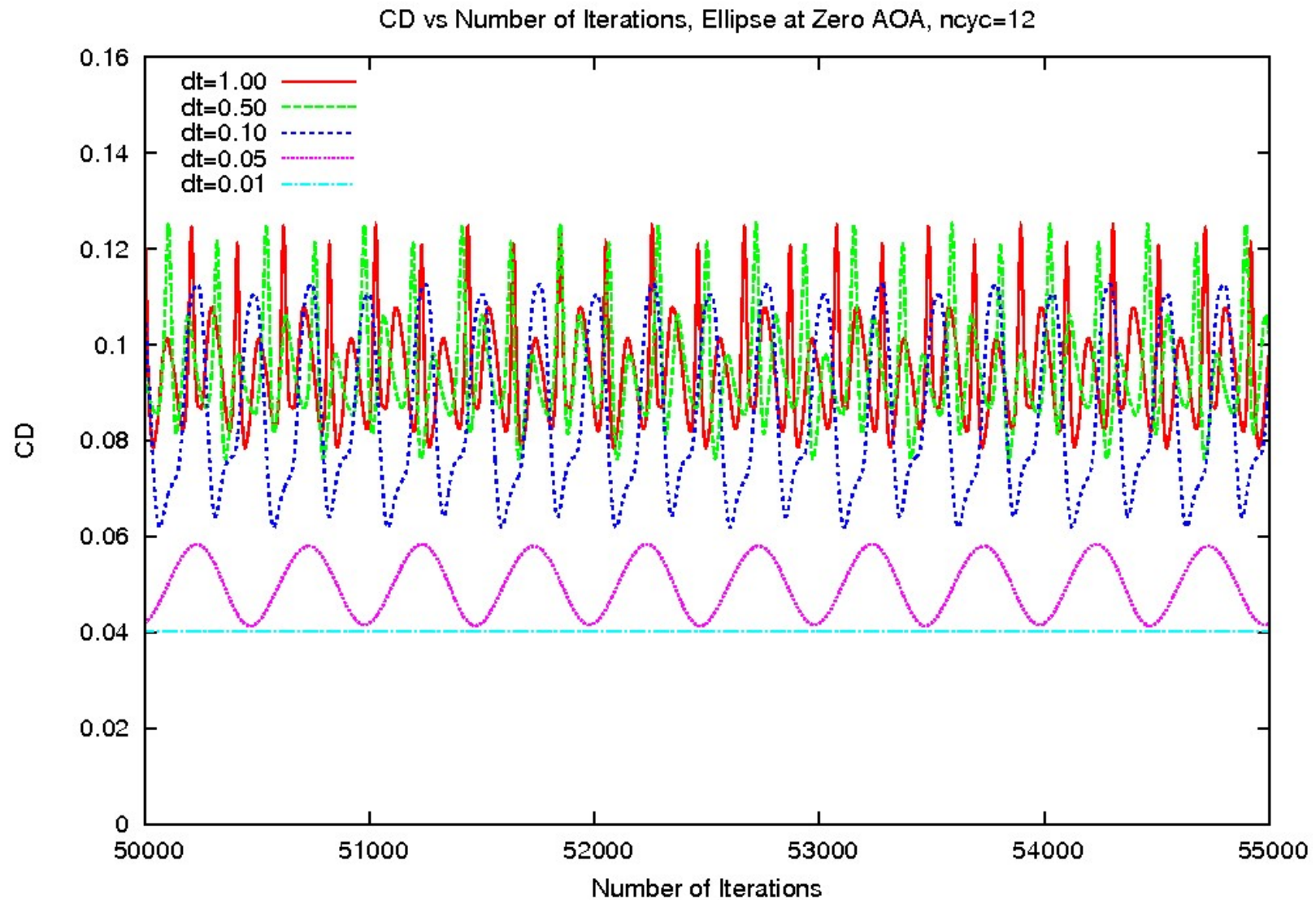


Dependence of C_L on Time Step, ncyc = 12

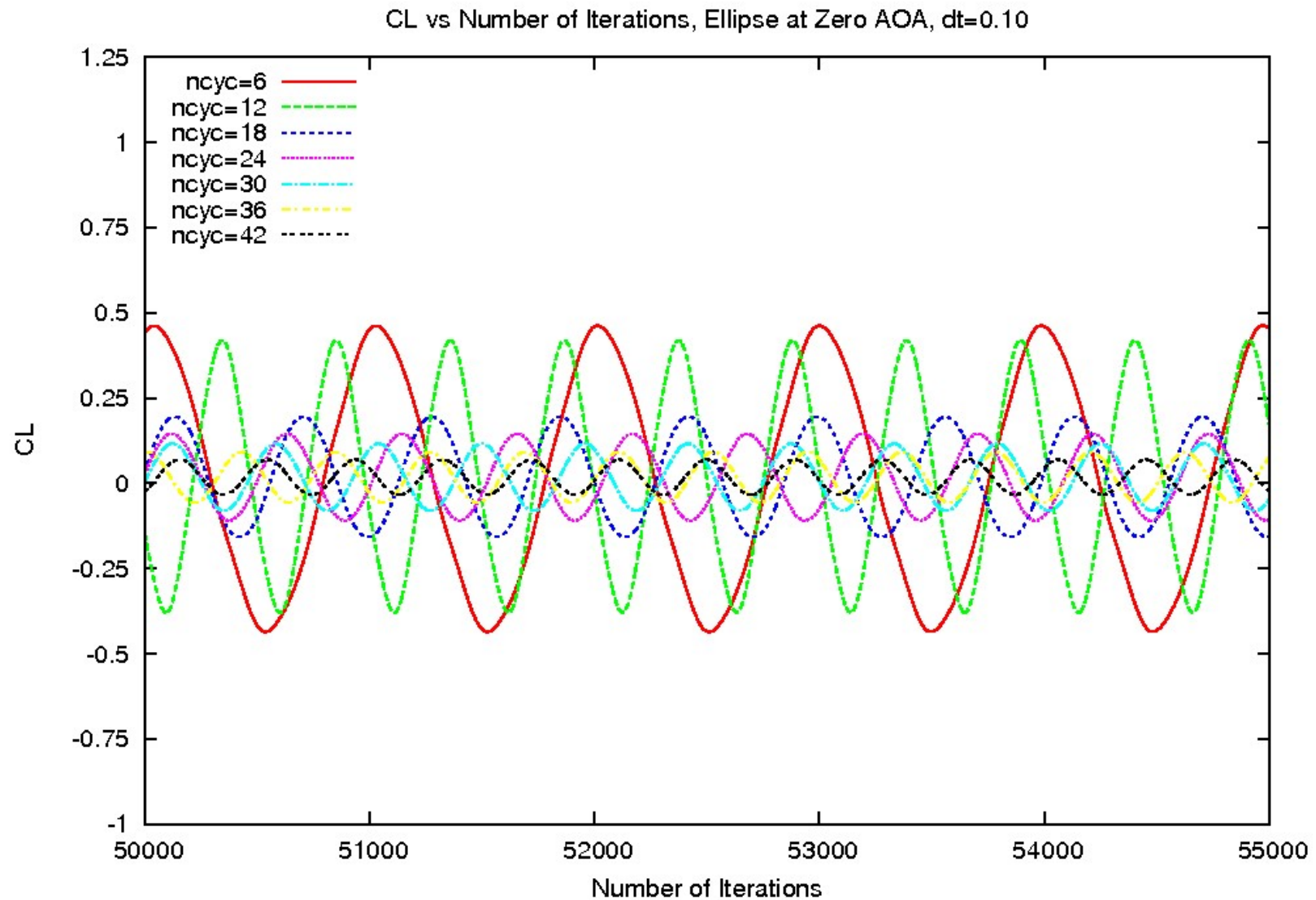




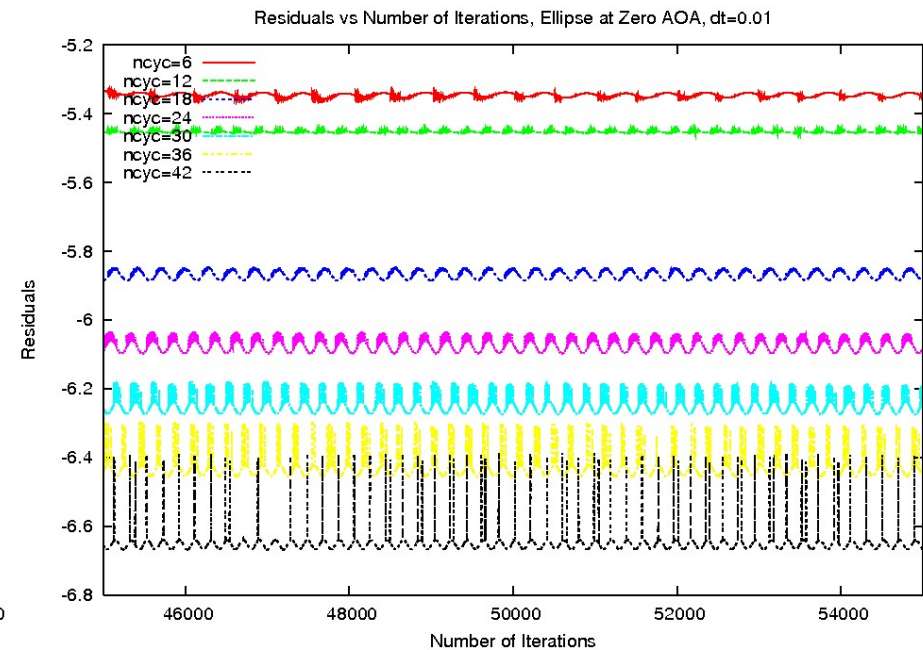
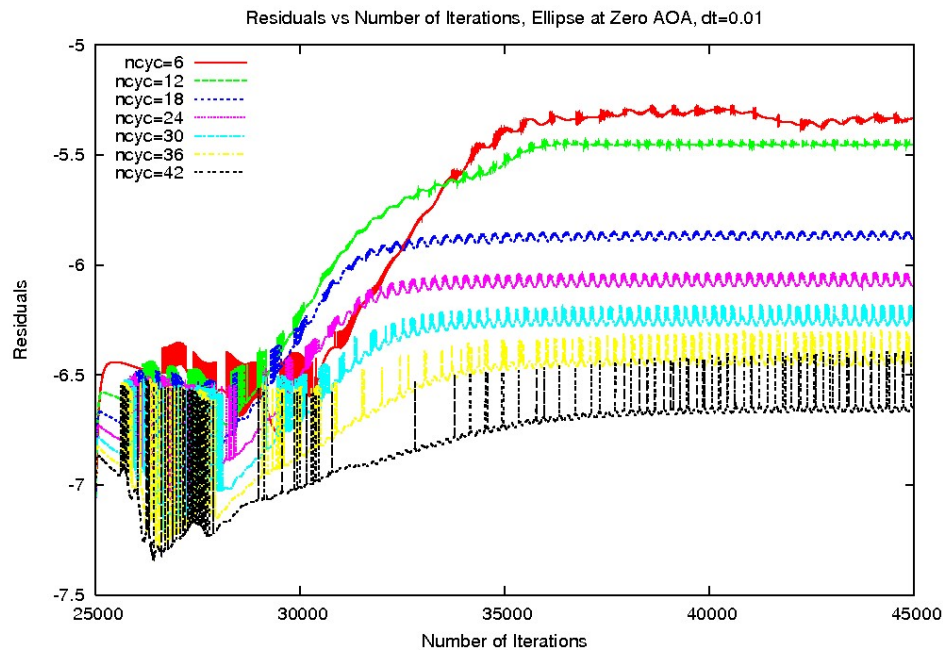
Dependence of C_D on Time Step, ncyc = 12



Dependence of Solution on # of Cycles, ncyc, $dt = 0.1$



Residuals



- As the solution becomes steady, the residuals decrease
- As the residuals decrease, frequent jumps appear in residual values
- Steady solution is not a good solution



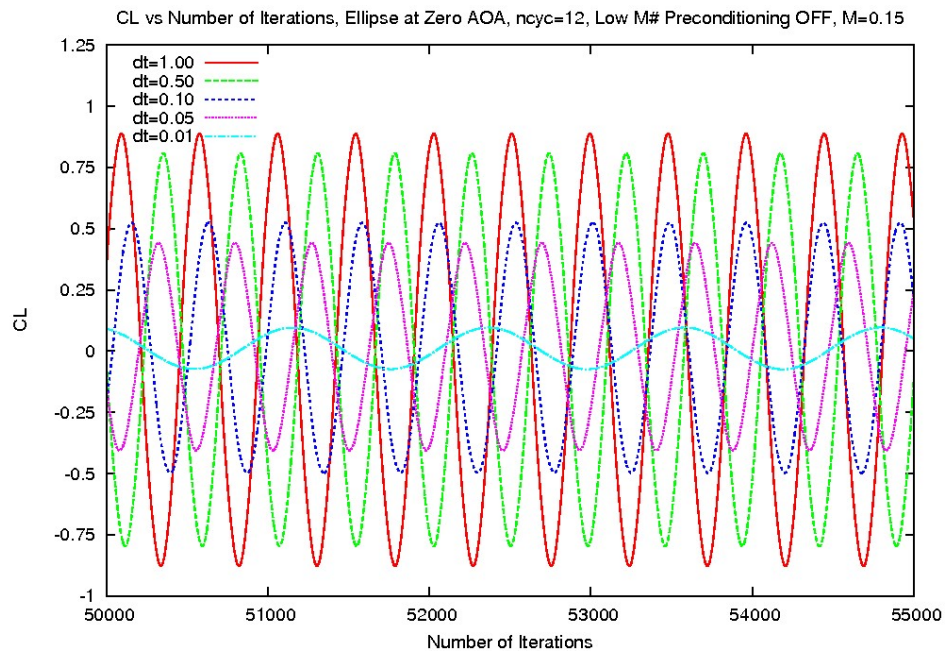
How can this be fixed?

1. Try increasing Mach number
 - Low Mach number preconditioning has known issues
2. Try running full Navier Stokes equations
 - Includes cross derivative terms not usually included in thin-layer approximation
3. Try running in series mode
 - Problem may be with splitting large grid into pieces
 - May be why solution was not resolved at boundaries

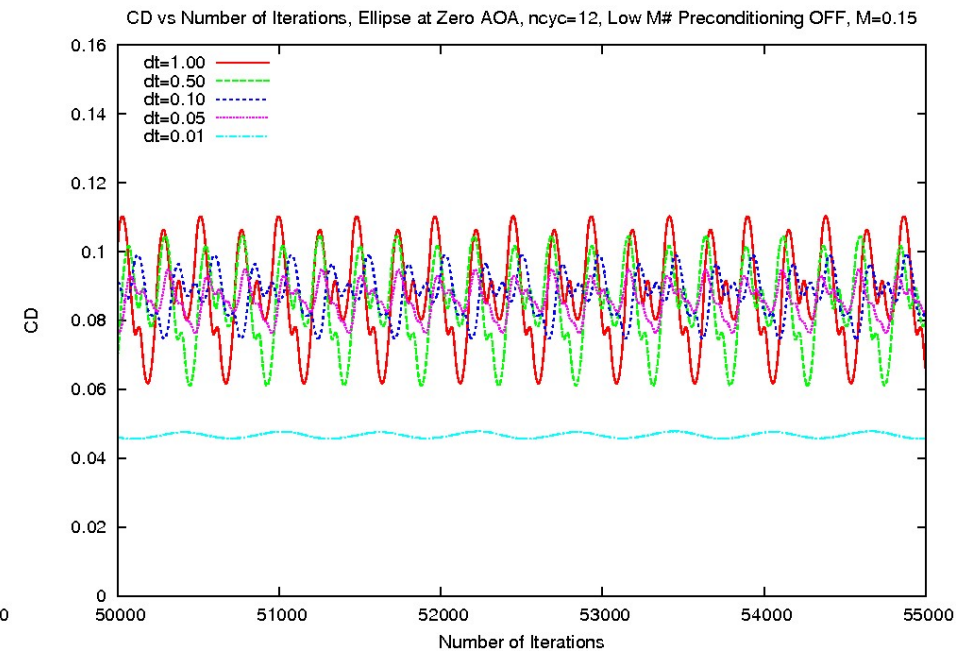
Higher Mach Number



C_L



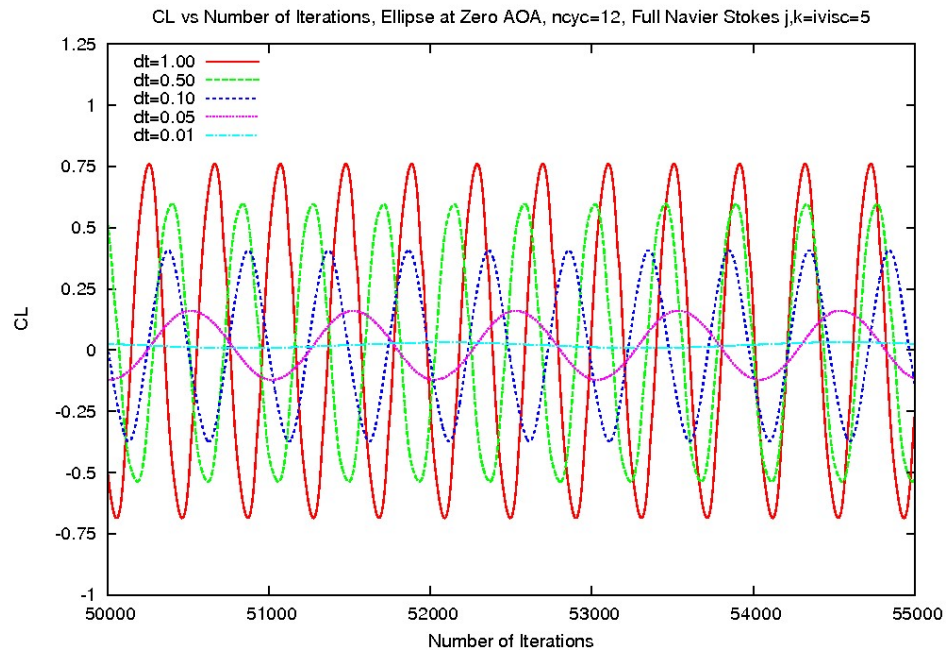
C_D



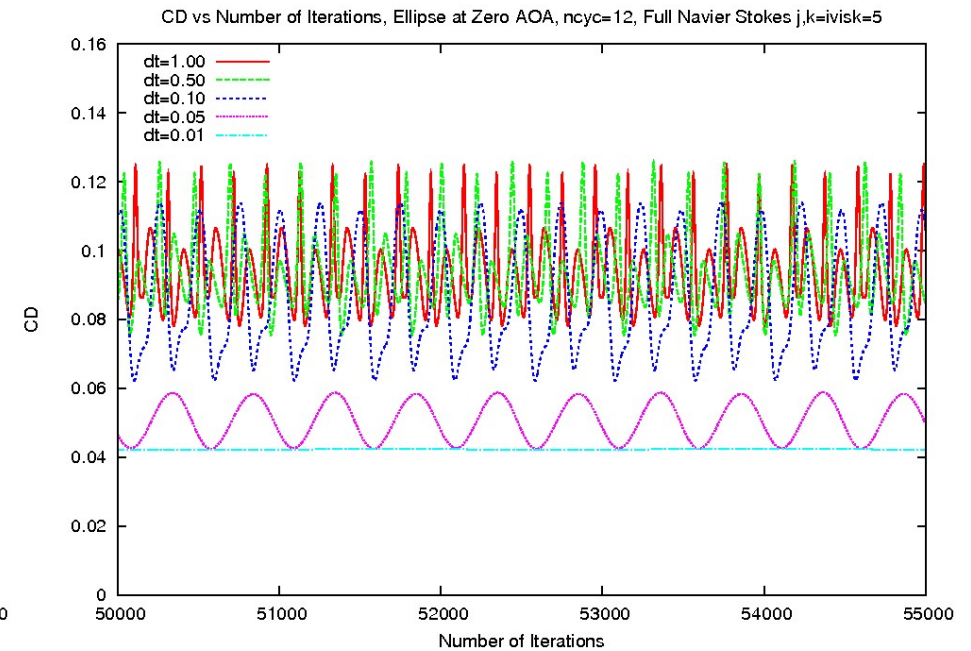
Full Navier Stokes



C_L



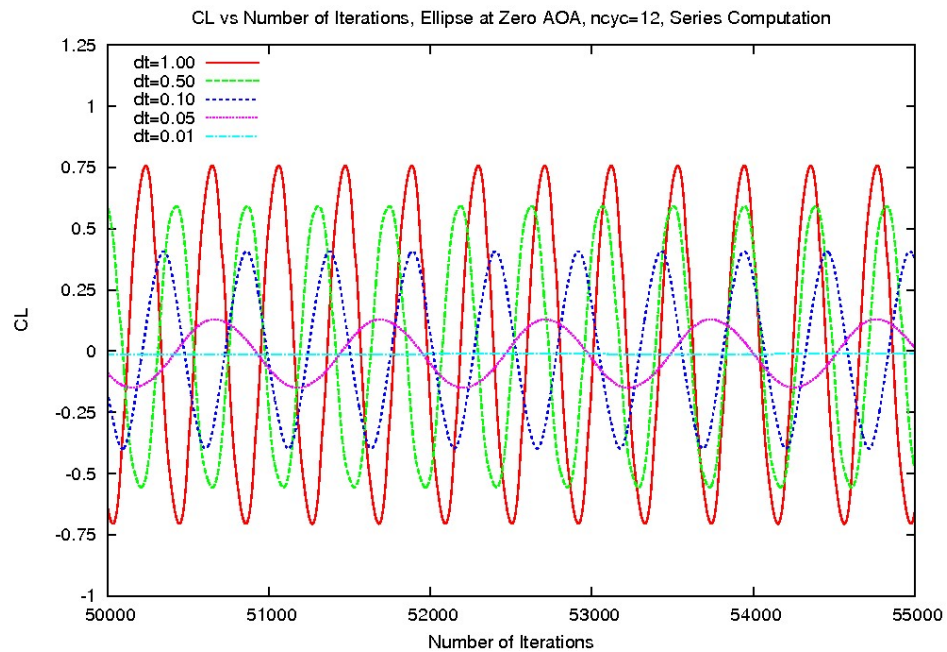
C_D



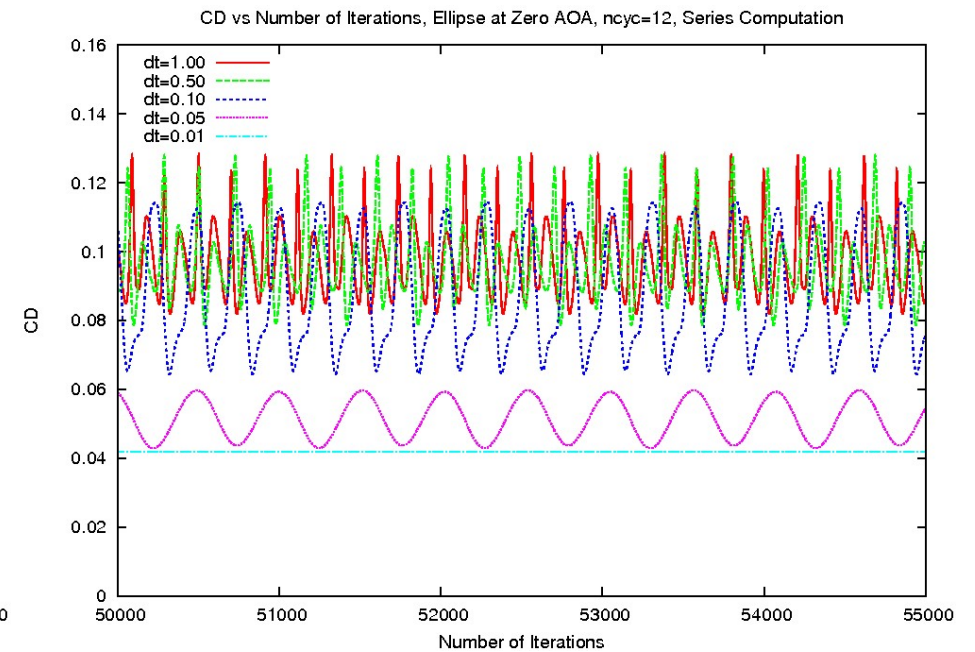
Series Computation



C_L



C_D



How else can this be fixed?

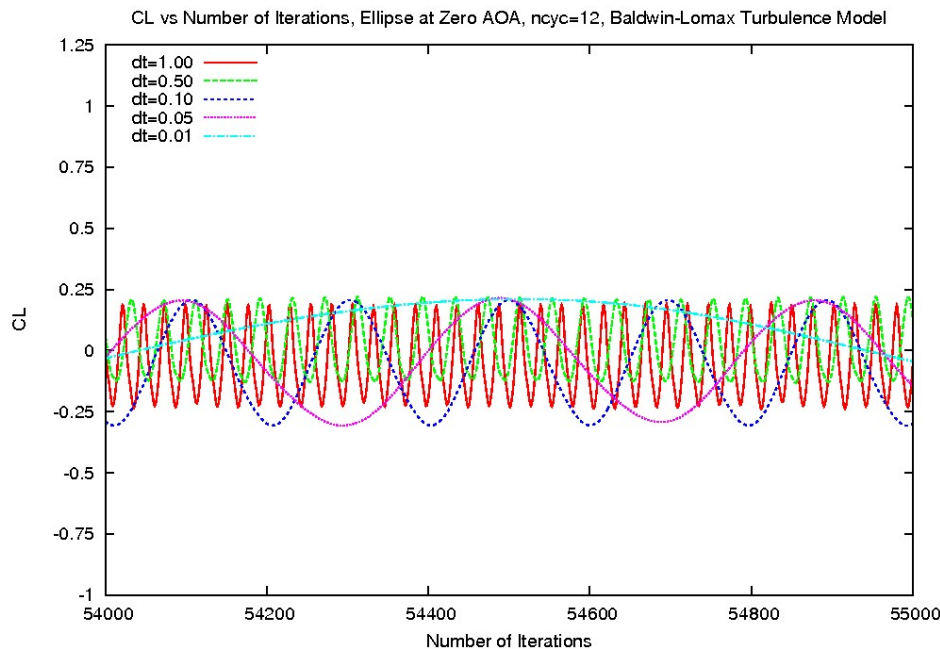


- Try employing another turbulence model
- Spalart-Allmaras model is robust model
 - Most commonly used model
 - But it is not working
- Baldwin-Lomax with Degani-Schiff modification is also known to be robust
 - Older model
 - Original model used by CFL3D

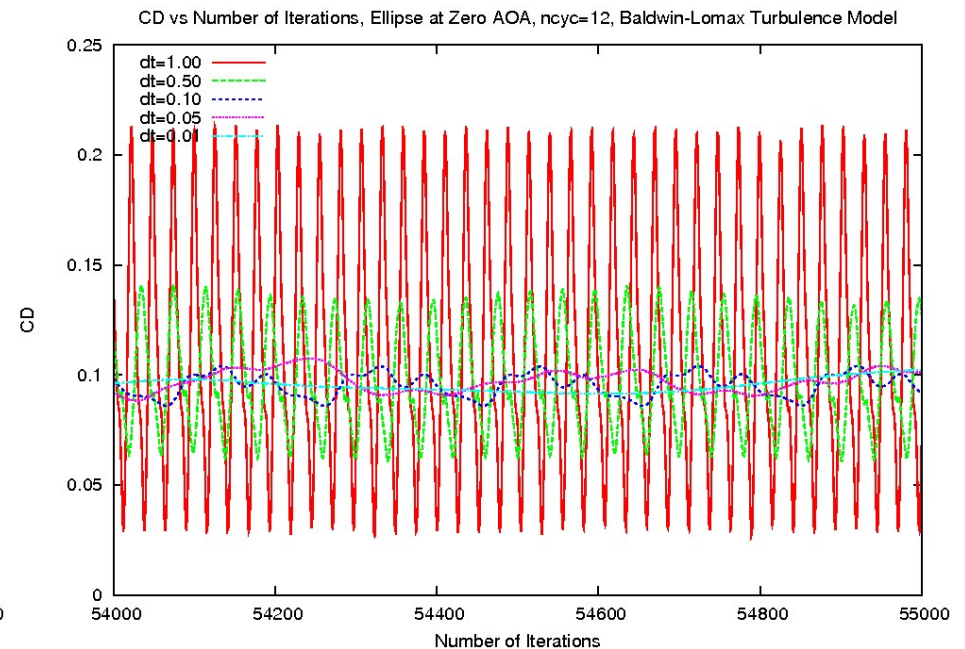
Baldwin-Lomax Model



C_L



C_D

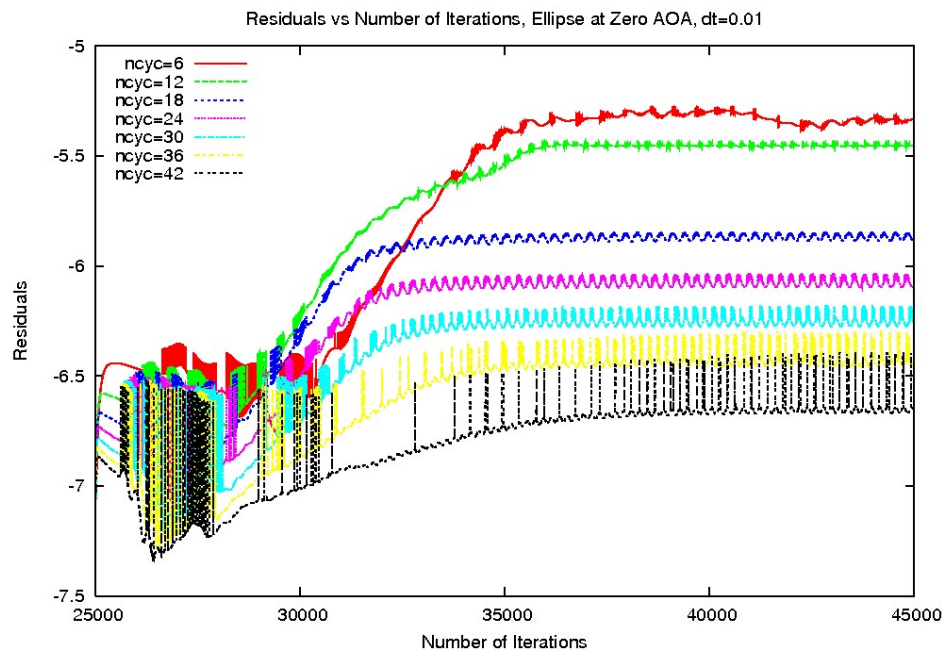


- surprisingly good results
- frequency and amplitude of oscillations independent of dt , $ncyc$
- for high values of dt , C_D oscillated too much
- but for high values of dt solution is not expected to be accurate

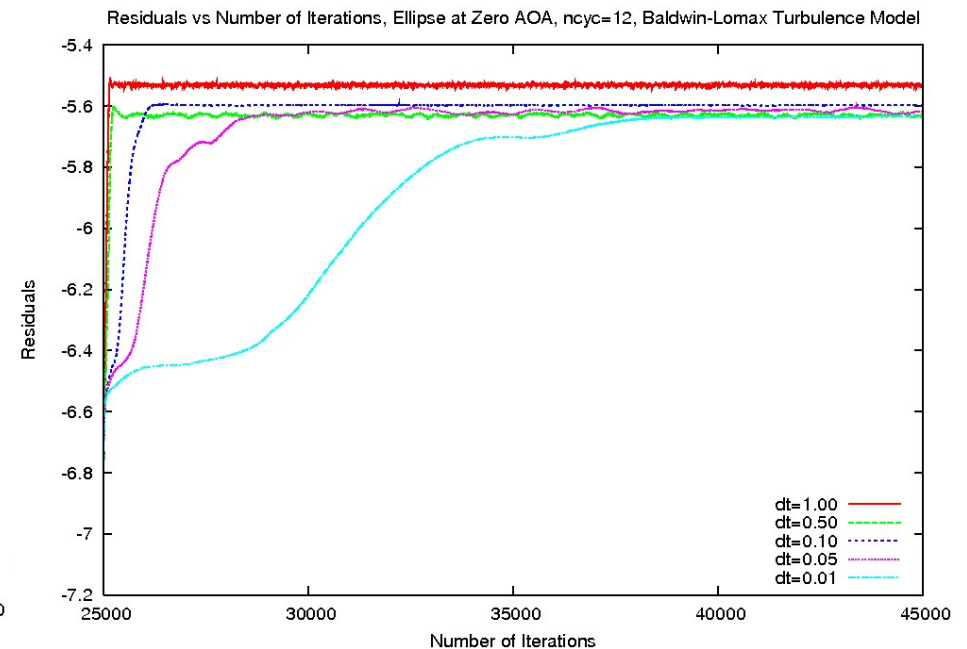
Residuals



Spalart-Allmaras Model

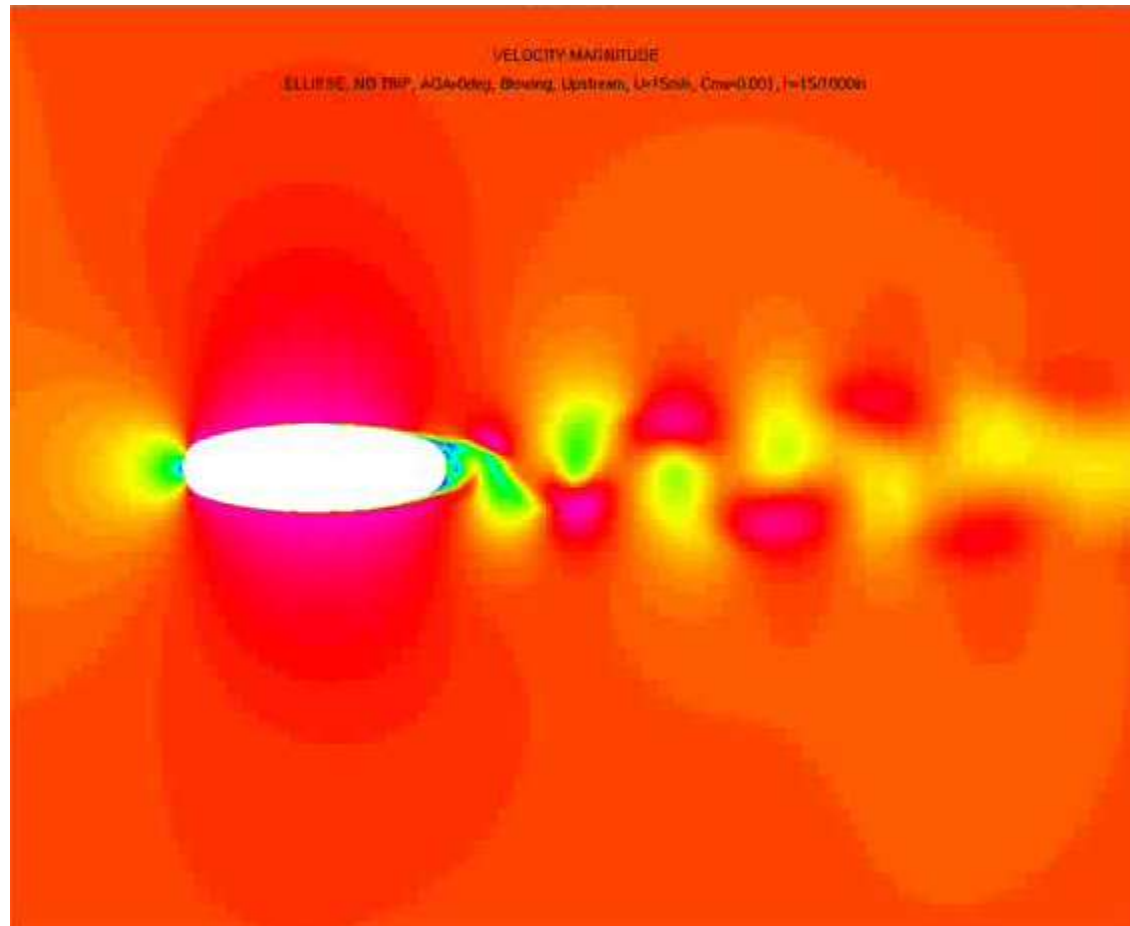


Baldwin-Lomax Model



- residuals are now in a reasonable range
- no observable jumps
- as dt decreases, the solution gets better, residuals decrease

Baldwin-Lomax Model

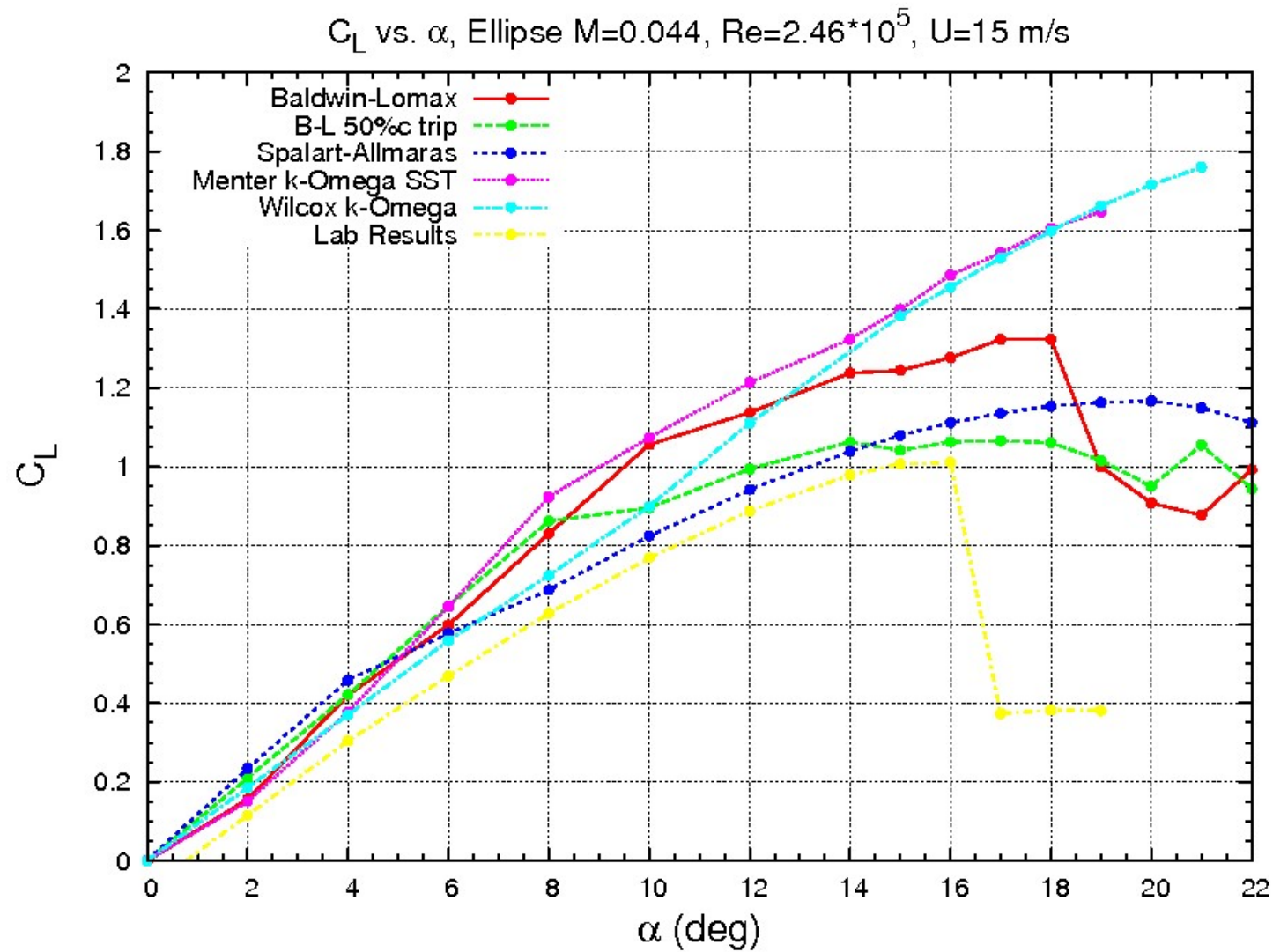




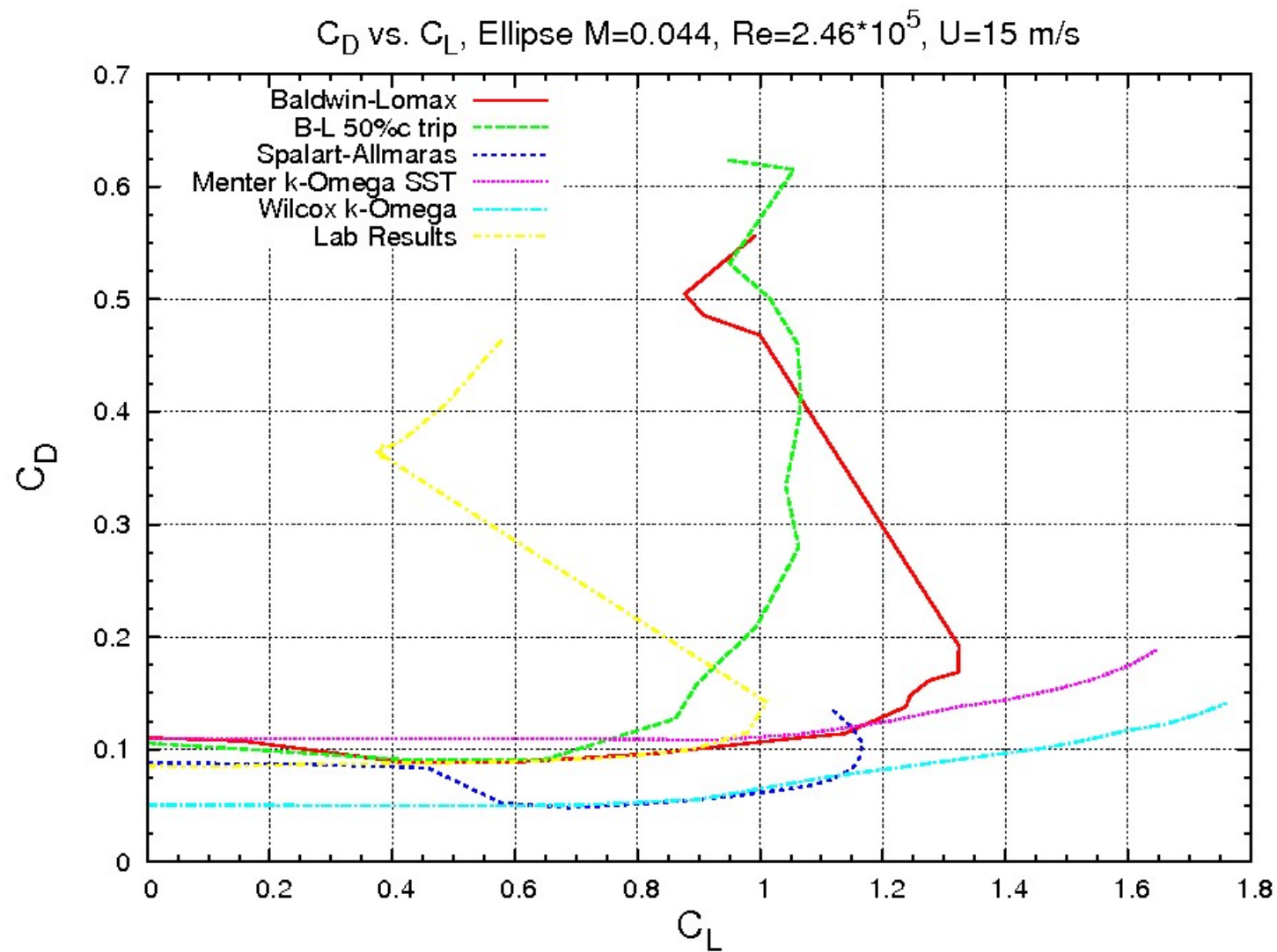
Study of Turbulence Models

1. Baldwin-Lomax
2. Spalart-Allmaras
3. Menter's k-Omega SST model
4. Wilcox k-Omega model

C_L vs. α



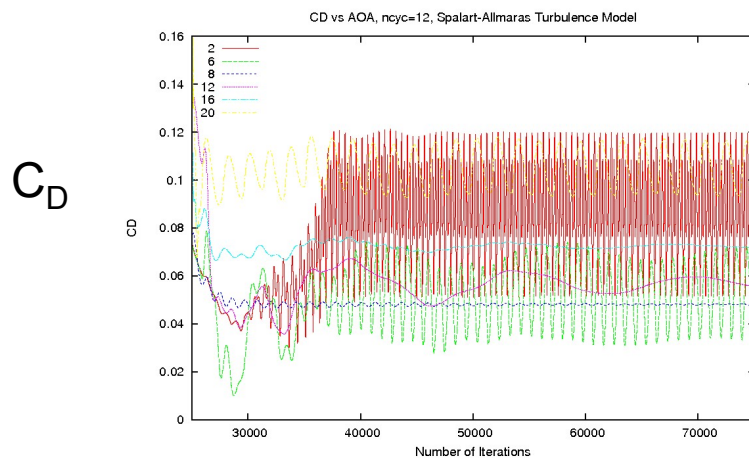
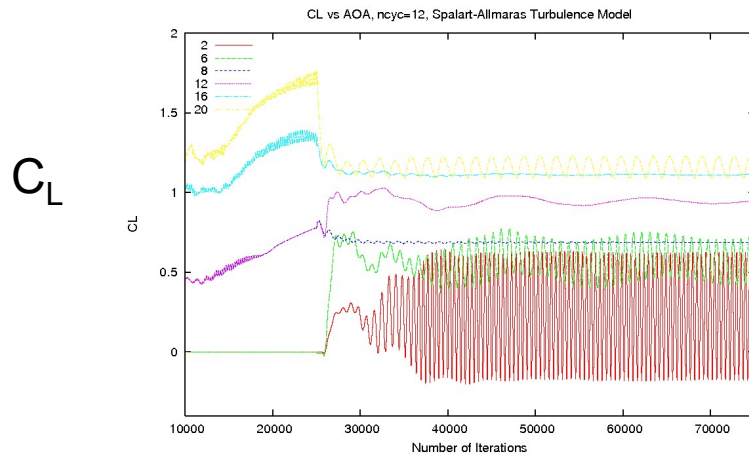
C_D vs. C_L



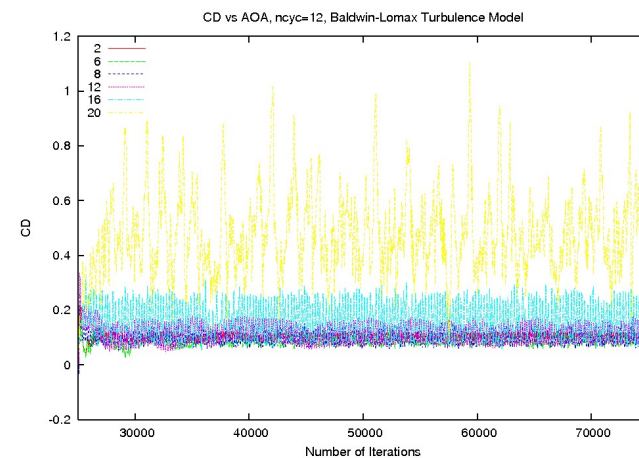
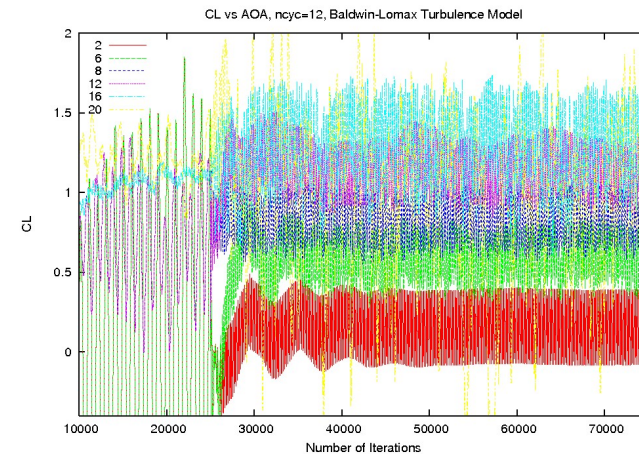


Time Dependent Behavior

Spalart-Allmaras Model



Baldwin-Lomax Model

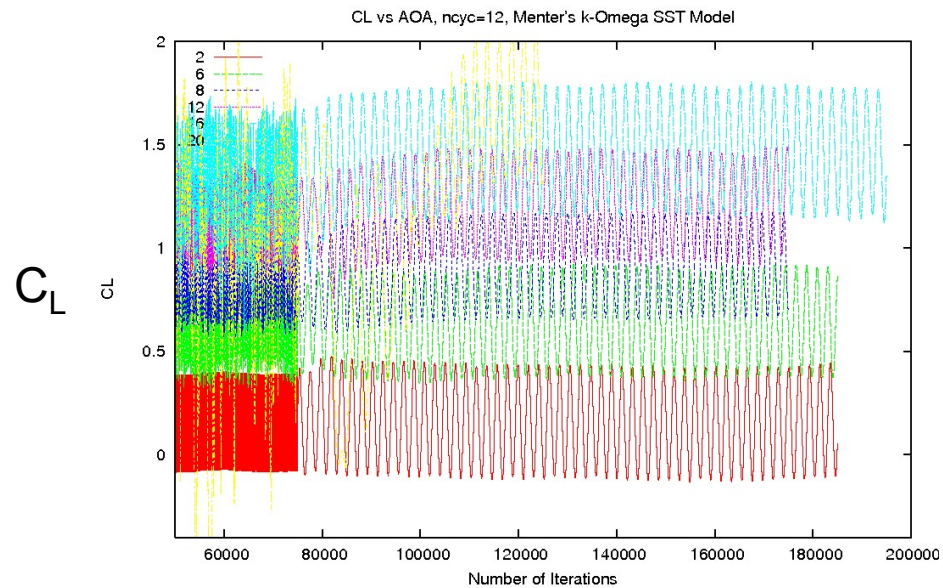


The angle of attacks of 2, 6, 8, 12, 16, and 18 are plotted

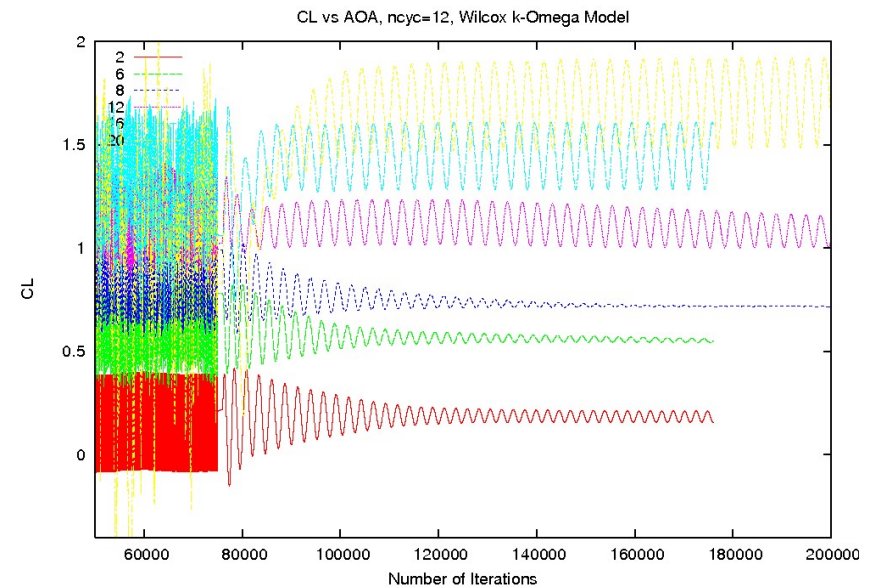
Time Dependent Behavior



Menter's k-Omega SST Model

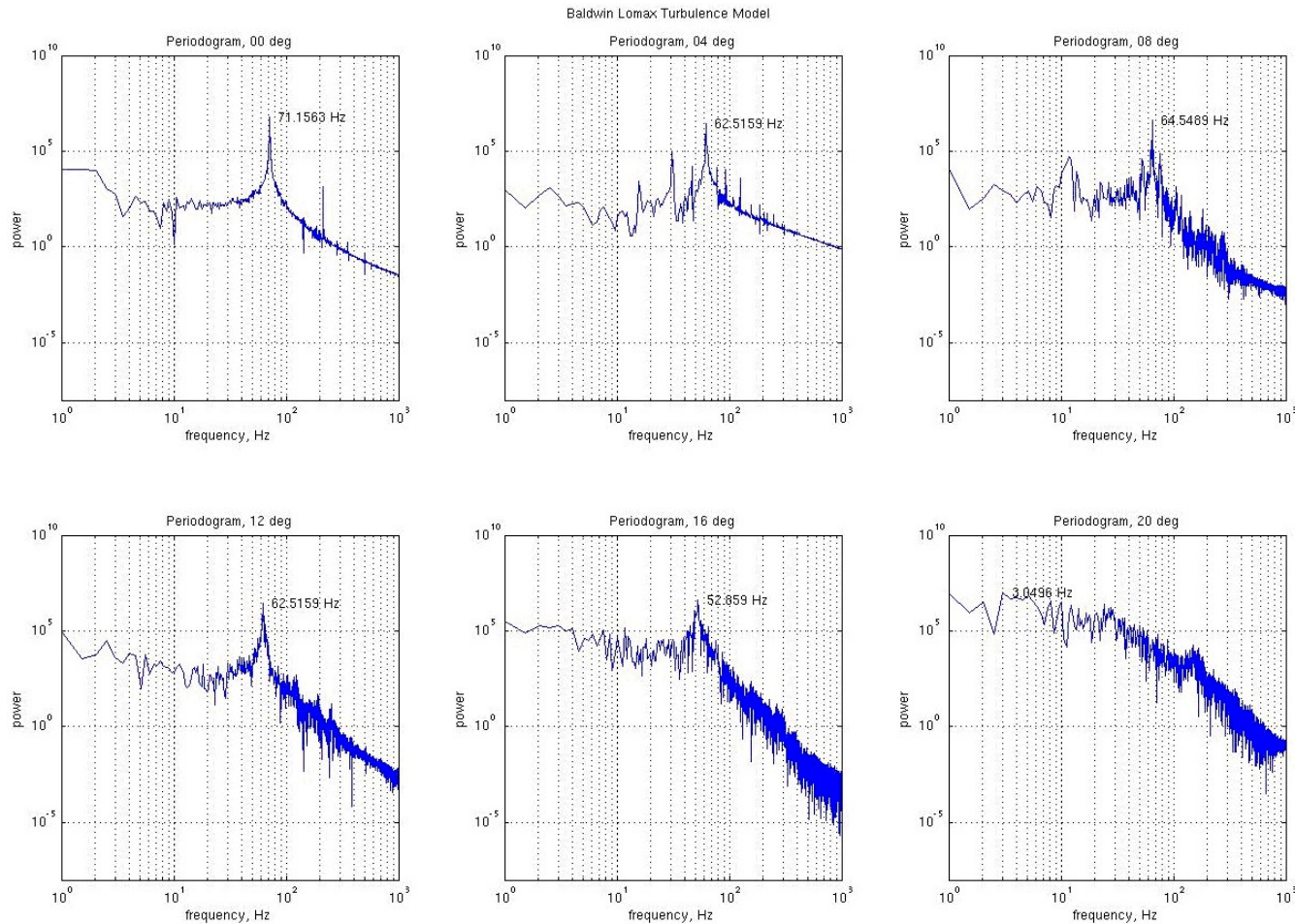


Wilcox k-Omega Model



The angle of attacks of 2, 6, 8, 12, 16, and 18 are plotted

Power Spectrum: Baldwin-Lomax





Power Spectrum Summary

Frequency range from $\alpha = 0$ to 20 degrees:

- Baldwin-Lomax 71Hz – 52Hz
 - Spalart-Allmaras 25Hz – 7Hz
 - Menter k-Omega 61Hz – 51Hz
 - Wilcox k-Omega 56Hz – 38Hz
-
- At zero AOA, the frequency should be about 65Hz in order to have a Strouhal number of 0.2 where $St = f \cdot L / V$
 - The Spalart-Allmaras model does not oscillate at a reasonable frequency
 - All other models predict frequencies that are somewhat close



Conclusions - 1

What was well predicted by the Spalart-Allmaras model?
(Time averaged results)

- Baseline Ellipse, C_L vs. α , C_p vs. x/c
- Baseline Ellipse with Cusp, C_L vs. α , C_p vs. x/c
 - Negative lift slope curve for small α
- Trailing Edge Blowing/Suction C_L vs. C_{μ}
 - C_L was underestimated for the ellipse
 - C_L was overestimated for the ellipse with a cusp
 - But the shape of the curve was well predicted for both
- Leading Edge Suction C_L vs. C_{μ} and C_D vs. C_{μ}
 - Hysteresis
 - Values of C_L and C_D
 - The value of C_{μ} necessary for recovery from stall



Conclusions - 2

Issues with Spalart-Allmaras model:

(Time dependent results)

- Converged to a steady solution
- Solution depended highly on Δt and n_{cyc}
- Residuals would make sudden jumps
- As AOA increased, solution went from unsteady to steady
- Predicted frequencies were unreasonable

Overall Spalart-Allmaras conclusions:

- Predicts various flow phenomenon with reasonable accuracy
- These predictions are limited to averaged values over time
- Time dependent behavior is poorly predicted

Conclusions about other models:

- Baldwin-Lomax was most robust with reasonable predictions
- Menter k- Ω SST predicted time-dependent behavior well
- Wilcox k- Ω model became steady at 8 degrees AOA